

# Key Differences between Radar and Communications Systems

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# Goals of Communications & Radar Systems

## ● Communications

- Transfer information from a source to a sink.
- Transmit signals through a channel connecting source and sink.

## ● Radar

- Detect the presence of targets and/or estimate their parameters.
- Radiate electromagnetic energy and gather information about the environment by observing echoes.

# Communications and Radar Systems

## Communications

- **Input:** Communications Signal
- **System:** Direct path and multipath
- **Output:** Noisy, distorted version of signal

## Radar

- **Input:** Radar waveform
- **System:** Targets in environment
- **Output:** Noisy echoes due to targets



# Radar vs. Communications

- Radar

“Given the radar waveform and the observed echoes, characterize the system.”

- Communications

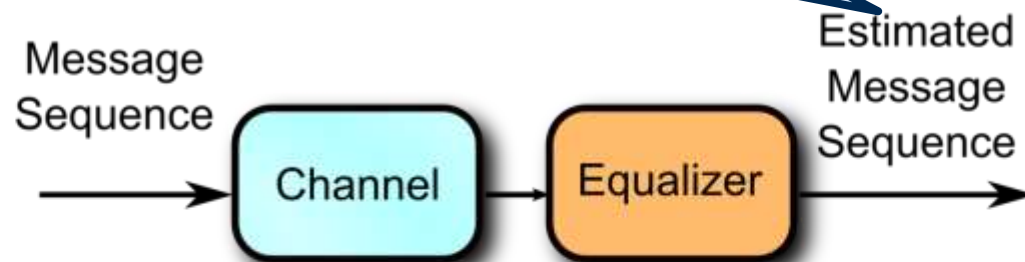
“Given knowledge of the system (channel) and an observation of the signal, estimate the transmitted signal.”



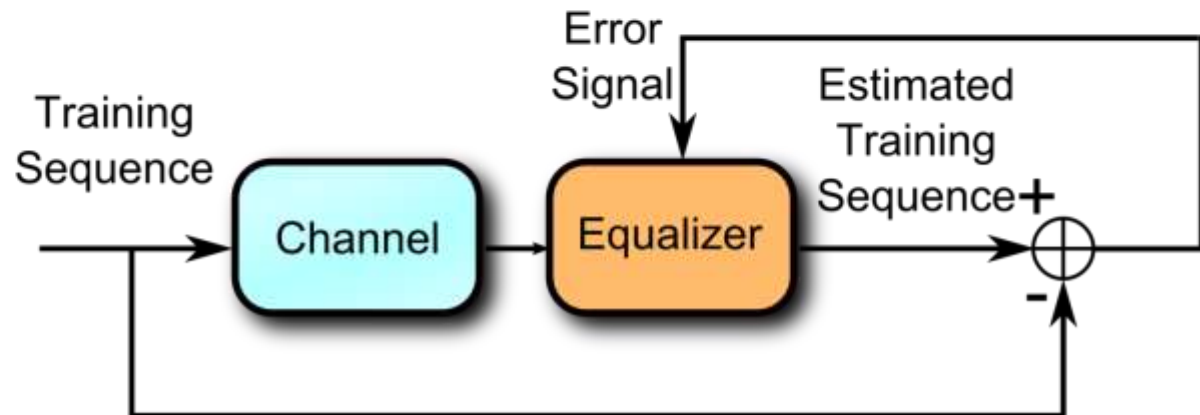
# Communications: Data Transmission

Receiver estimates message sequence given knowledge of how the channel responds to certain inputs.

Data Transmission



Channel Sounding



# Communications: Channel Sounding

Data Transmission

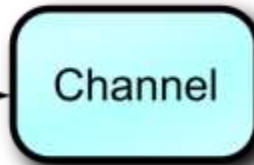
Message Sequence



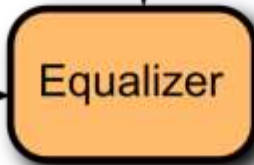
Train equalizer by observing outputs corresponding to certain inputs.

Channel Sounding

Training Sequence



Error Signal



Estimated Training Sequence+



Known to both transmitter and receiver.

# Radar vs. Channel Sounding

- In communications, the characteristics of the channel are nuisance parameters that must be accounted for but are of no inherent importance.
- In radar, the “channel” and its characteristics are of primary interest.
- Example: The Channel Impulse Response
  - Each time tap is due to the direct path or scattering from reflectors at a particular range.
  - Comms Apply an equalizer to compensate.
  - Radar Use multiple pulses to resolve in cross-range.

# Radar Missions

- **Detect presence of targets at particular locations/Dopplers.**
- **Ground moving target indication (GMTI)**
- **Air moving target indication (AMTI)**
- **Estimate parameters of targets at a particular location**
- **Synthetic aperture radar (SAR) imaging**



# Detection vs. Estimation

- Radar systems typically search a volume/surface for targets by scanning a directional beam. Within each beam position, the decides if a target is present at a particular range/Doppler by calculating the likelihood ratio.
- After synchronization, communications systems estimate the chip value for a particular modulation chip by calculating the maximum a posteriori (MAP) estimate.

# Radar vs. Communications “Links”

## ● Propagation Losses

- One-way comms propagation models usually assume something on order of  $R^2 / R^3$
- Radar is a two-way channel, so ERP must account for  $R^4$  propagation loss.

## ● Direct path vs. Multipath

- Comms may include direct path or reflections off of surface.
- Radar returns are always due to scattering, which may require increased power for “small” targets.

# Radar vs. Communications “Capacity”

- **Communications channels may be bandwidth limited, so increasing transmit power may be of limited utility.**
- **Some radars can increase search volumes by increasing transmit power and decreasing dwell times.**

# Radar Waveforms: Coherence Requirements

- Coherent radar systems require signal to have some spectral support for a specified coherent processing interval (CPI)
- Airborne pulse-Doppler radars transmits a series of identical pulses to suppress clutter. (CPI on order of milliseconds)
- Synthetic aperture radar (SAR) forms high resolution imagery of the ground by transmitting a sequence of pulses. (CPI may be on order of seconds, during which the waveform cannot change significantly)

# Radar vs. Communications Antennas

- **Mobile units of communications systems typically employ nearly omnidirectional antennas.**
- **Radar systems typically scan a high-gain antenna over a specified surveillance volume/search area/scene to be imaged.**
- **Incident power density of radar system may fluctuate rapidly due to antenna scan.**

# Radar Development Cycle: SPY 1

- First installed on USS Norton Sound, 1973.
- Entered active service in 1983 as SPY-1A.
- Subsequently upgraded to B/D and D(V) versions.
- Currently deployed on about 100 surface ships.



“SPY-1 is the most widely fielded naval phased array radar in the world. It is the heart of the Lockheed Martin-developed Aegis Weapon System. It automatically detects and tracks hundreds of targets from the wave tops to the exoatmosphere.”

-LM Brochure

# Summary

- **Radar and communications exploit similar electromagnetic phenomena and are well described by similar mathematical theories.**
- **Significant differences in operational requirements exist between the two.**