

# An Air-to-Ground HF Propagation Prediction Model for Fast Multicircuit Computation

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## LIST OF SYMBOLS

$A_i$	=	height-related factor, defined by (41)
$B$	=	empirical constant, used in (28)
$b$	=	bandwidth, Hz
$b_i, i=1,2$	=	bearings from transmitter to receiver and vice versa
$C$	=	empirical constant, used in (28)
$D$	=	ray path length, km
$D_\delta$	=	upper decile of atmospheric noise, dB
$D_u$	=	lower decile of atmospheric noise, dB
$D_i, i=1,2$	=	distance from antenna $i$ to ground reflection point, km
$d$	=	great circle path length, km
$d_i, i=1,2$	=	distances used in curve-fitting, (52-56)
$e_n$	=	error in iterate for $\sin \beta$ , (43)
$f$	=	frequency, MHz
$f_c$	=	critical frequency, MHz
$f_H$	=	gyrofrequency, MHz
$f_v$	=	equivalent vertical frequency, MHz
$G_R$	=	receiver antenna gain, dB
$G_T$	=	transmitter antenna gain, dB
$h$	=	true height of reflection, km
$h_E$	=	height of maximum electron density of E-layer
$h_{max}$	=	height of maximum electron density
$h_i, i=1,2$	=	antenna heights, km
$h'$	=	virtual height of reflection, km
$\Delta h$	=	retardation.
$j$	=	$\sqrt{-1}$
$K$	=	correction factor given by (9)

$k$	=	Boltzman's constant
$L$	=	path loss, dB
$L_{bf}$	=	free space loss, dB
$L_g$	=	ground reflection loss, dB
$L_i$	=	ionospheric absorption loss
$m$	=	exponent in (17), given by (18)
$N$	=	noise power
$N_g$	=	median galactic noise power in 1 Hz bandwidth
$N_m$	=	median man-made noise power in 1 Hz bandwidth
$N_o$	=	median atmospheric noise power in 1 Hz bandwidth
$n$	=	number of skywave hops
$P_E$	=	effective radiated power, watts
$P_t$	=	transmitter power, dBW
$Q$	=	spherical surface impedance, (47)
$q_f$	=	chi-square probability distribution, (27)
$R$	=	circuit reliability, (57)
$R_g$	=	$R_V$ or $R_H$ , ground reflection coefficient
$R_H$	=	ground reflection coefficient for horizontal polarization
$R_V$	=	ground reflection coefficient for vertical polarization
$R_o$	=	"numerical distance," (35)
$r_o$	=	radius of earth, km
$S$	=	signal strength, dBW
$S_n$	=	$n$ th approximation to $\sin \beta$ , (44)
$S_{13}$	=	smoothed 13-month sunspot number
$s_x$	=	subsolar latitude
$s_y$	=	subsolar longitude
$T_o$	=	reference temperature, 288°K
$t$	=	variable of integration in (46)

$t_0$	=	apex of integration contour in (46)
$t_g$	=	universal time
$u$	=	$f_0E/(f \cos \alpha)$
$V$	=	mismatch polarization loss, $V$
$v$	=	scaling factor, (47)
$W$	=	winter anomaly factor, (17)
$X$	=	$V\theta$ , (47)
$x_i, i=1,2$	=	latitude
$y$	=	$\gamma h/V$ , used in (50)
$y_E$	=	semi-thickness of E-layer
$y_n$	=	semi-thickness of layer
$y_i, i=1,2$	=	longitude
$Z$	=	scaled ratio of critical frequencies, (26)
$z$	=	scaled numerical distance, (37)
$\alpha$	=	angle of incidence of unrefracted ray at E-layer maximum
$\beta$	=	take-off angle
$\gamma$	=	$2\pi/\lambda$ , the wave number
$\Delta$	=	angle ray is bent, (13).
$\delta$	=	ground surface impedance, (34)
$\epsilon$	=	relative dielectric constant of ground
$\eta$	=	refractive index of ground, (23)
$\theta$	=	great circle path length, radians
$\lambda$	=	radio wave length in free space
$\nu$	=	collision number in ionosphere
$\xi$	=	number of degrees of freedom in $\chi^2$ distribution
$\sigma$	=	ground conductivity, mho/m
$\phi$	=	angle of incidence on ionosphere
$\chi^2$	=	"value related to $f$ ," (27)



$\psi$  = solar zenith angle  
 $\psi_{12}$  = solar zenith angle at noon  
 $\omega=2\pi f$  = angular frequency



# AN AIR-TO-GROUND HF PROPAGATION PREDICTION MODEL FOR FAST MULTICIRCUIT COMPUTATION

F. G. Stewart, L. A. Berry, C. M. Rush,\* and V. Agy\*\*

A radio propagation prediction computer code has been developed to permit rapid simulation of HF air-to-ground telecommunication circuits. This prediction program provides estimates of both skywave and groundwave HF propagation parameters. The skywave and groundwave propagation parameters can be obtained for radio circuits with transmitters and receivers on the surface of the earth or with one or both ends of the circuit elevated up to 50 km. When a large number of circuits in a given area are simulated for a single time, the program is an order of magnitude faster than its predecessors. This report provides a description of the air-to-ground HF propagation prediction program as well as illustrations of the results obtained from the program.

Key words: air-to-ground propagation; groundwave propagation; HF predictions; ionospheric propagation; propagation predictions; skywave propagation

## 1. INTRODUCTION

High frequency (3-30 MHz) radio waves that are reflected from the ionosphere are used extensively for communications over distances well beyond the optical horizon. Such communications are used for international broadcasting services, for message traffic between two fixed points on the earth, or between moving terminals. In addition to propagating via the ionosphere, HF radio waves can propagate over the surface of the earth via the conventional groundwave. Groundwaves that travel along the surface of the earth may be of operational use out to distances of the order of 100-300 km from the transmitter.

High frequency skywave signal strengths vary relative to the ionosphere: hour-to-hour, diurnal, seasonal, solar cycle, and spatial. The performance of telecommunication systems that rely upon HF skywave signals is dependent on transmitter power, transmitted frequency, transmitter and receiver antenna characteristics, and the noise and interference environment in which the system must operate. The performance of telecommunication systems relying on HF groundwave is dependent upon the same parameters as well as the type of ground over which the signal is propagated.

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Many numerical methods have been devised to permit calculation and prediction of the performance of HF telecommunication systems that rely upon skywave or groundwave propagation. The most useful of these methods invariably form the bases of complex computer programs that are recognized and used by system designers and propagation scientists worldwide. The skywave prediction methods of general use include those reported by Barghausen et al. (1969), the CCIR (1982 a and b), Bradley (1975), and John Lloyd (private communication, 1983). The groundwave prediction methods for HF systems that are of general use include those reported by Berry and Herman (1971), Ott (1971), and Hill (1982).

For the most part, the numerical methods to predict HF field strength treat either skywave or groundwave, but not both. In most instances of HF field propagation applications the user desires information regarding either skywave characteristics or groundwave characteristics. Generally, the distance between the terminals of a given HF circuit is such that only skywave (greater than 100 km) or groundwave (less than 100-300 km) signals provide sufficient amplitude for the required time periods to be operationally useful. A notable exception, however, occurs when consideration is given to the situation in which one terminal (or more) of an HF system is mobile or has the capability of becoming mobile. In this case, the transmitter and receiver locations can vary from essentially being colocated to being separated by distances far beyond the horizon. Depending upon the particular geometry, both skywave and groundwave signals need to be considered in predicting or assessing the performance of the HF system.

In this report, an HF propagation prediction program is described that permits calculation of both skywave and groundwave signal characteristics for path geometries that are specified by the user. The program has been optimized to rapidly calculate a large number of HF air-to-ground circuits in an area at a given universal time. The calculations can be performed for any number of propagation paths, and the transmitters and/or receivers can be located anywhere in altitude from the surface of the earth to 50 km. The primary use of the program is expected to be for circuits spanning distances from 0 to 2000 km, but it is not limited to these distances.

The HF propagation program that is reported herein relies on two distinct programs developed at the Institute for Telecommunication Sciences. The skywave prediction method used essentially follows from the HF prediction program developed by Barghausen et al. (1969). The groundwave prediction method used is based on work described by L. A. Berry (OT Technical Memorandum 78-247, January 1978). The air-to-ground prediction program derived from these two programs is optimized

for calculations for a large number of air-to-ground HF circuits operating simultaneously. In the next section, the skywave propagation prediction methodology is described. The description is brief for those parts of the skywave method that are exactly the same as given by Barghausen et al. (1969). More detailed discussion is given to areas of the prediction method where changes were made to speed up the calculations, particularly for the estimation of ionospheric parameters and atmospheric noise. In Section 3, the groundwave prediction methodology is presented. The output from Berry's groundwave prediction program was fitted with parametric curves that produce rapid estimates of the groundwave propagation loss.

In Section 4, the results of a number of calculations of circuit performance are given to illustrate the wide range of application of the prediction program. In addition, estimates are given of the decrease in program running time because of the optimization. In Section 5, overall conclusions drawn from this effort are provided and recommendations for further work are put forth.

## 2. HF SKYWAVE PREDICTION METHOD

The skywave prediction technique employed in the current air-to-ground circuit simulation follows rather closely that of Barghausen et al. (1969). This program is referred to by many HF skywave prediction users as HFMUFES. In this discussion the program will be referred to as either HFMUFES or Barghausen et al. (1969).

The propagation program predicts monthly median operational parameters that characterize an HF skywave circuit such as maximum usable frequency (MUF), optimum traffic frequency (FOT), and lowest useful frequency (LUF) in terms of the probability of successful transmission for a particular circuit. The probability of successful transmission depends on the probability that the transmission frequency is below the critical frequency (i.e., the maximum frequency for reflection) of the F2 layer and the probability that the available signal-to-noise ratio is above a specified level.

The performance of an HF skywave circuit depends upon the path geometry, the strength of the signal at the receiver, the structure of the ionosphere, and the noise and interference environment in which the circuit must operate. In the air-to-ground program the same path geometry as in the HFMUFES program is used. The signal strength is determined, also, using the same loss terms as in the HFMUFES program. The ionospheric structure and the noise environment have as their basis the same models as in the HFMUFES program; however, the application of the numerical coefficients to determine the ionospheric structure and the atmospheric noise characteristics differs substantially from the HFMUFES program.

## 2.1 Path Geometry

To determine the operational parameters for an HF ionospheric radio communication circuit, it is necessary to calculate several parameters that are based on the geometry of the path. These include the path length, path bearings, and zenith angle of the sun.

The path length, which is taken to be the shorter of the great-circle distances between the two points, is computed as follows (Barghausen et al. (1969), equation 5.1):

$$\cos \theta = \sin x_1 \sin x_2 + \cos x_1 \cos x_2 \cos(y_1 - y_2) \quad (1)$$

where

- $x_1$  = geographic latitude of transmitter,
- $y_1$  = geographic longitude of transmitter,
- $x_2$  = geographic latitude of receiver,
- $y_2$  = geographic longitude of receiver, and
- $\theta$  = path length in radians.

Having obtained the path length, the bearing of transmitter to receiver and receiver to transmitter along the great-circle path is calculated as follows (Barghausen et al. (1969), equations 5.2 and 5.3):

$$\cos b_1 = (\sin x_2 - \sin x_1 \cos \theta) / \cos x_1 \sin \theta \quad , \quad (2)$$

and

$$\cos b_2 = (\sin x_1 - \sin x_2 \cos \theta) / \cos x_2 \sin \theta \quad , \quad (3)$$

where

- $b_1$  = bearing transmitter to receiver in radians, and
- $b_2$  = bearing receiver to transmitter in radians.

The zenith angle of the sun is needed to determine the appropriate ionospheric structure and noise environment for each hour of the day. It is used in calculating the ionospheric loss or absorption factor and is computed from the following equation (Barghausen et al. (1969), equation 5.7):

$$\cos \psi = \sin x_n \sin s_x + \cos x_n \cos s_x \cos(s_y - y_n) \quad , \quad (4)$$

where

$x_n$  = latitude of the point in question,  
 $y_n$  = longitude of the point in question,  
 $s_y$  =  $15 t_g - 180$  = subsolar longitude,  
 $t_g$  = universal time,  
 $s_x$  = subsolar latitude for the middle of the month, and  
 $\psi$  = sun's zenith angle.

In this program only five ray paths can be evaluated for each circuit and frequency. The ray path must be geometrically possible for a takeoff angle equal to or greater than the value given as input data. The skywave paths evaluated are two ray paths via reflections from the regular E layer or  $E_s$  layer and three ray paths via reflections from the F layer.

The E-layer modes considered are, first, the mode with the least number of hops possible for the given takeoff angle and, second, the mode with the next greater number of hops. If the calculations indicate that the ray at any particular frequency penetrates the E layer, then the sporadic-E mode may be investigated if desired. This is included as a program option.

The first F-layer mode considered is the mode with the least number of hops geometrically possible, taking into account not only the lower limit of the given takeoff angle, but also the cutoff effect of the E layer. The sporadic-E layer is always considered transparent for F-layer propagation. The next two F modes have successively higher hop numbers.

For any given circuit, parabolic layer theory is used to calculate the maximum usable frequency (MUF) and the takeoff angle  $\beta$  and virtual height  $h'$  of reflection of all frequencies.

The problem resolves into the solution of the equation

$$f = f_v K \sec \phi , \quad (5)$$

where

$f$  = the probing frequency at oblique incidence,  
 $f_v$  = the equivalent vertical-incidence frequency,  
 $K$  = a correction factor resulting from curved geometry, and  
 $\phi$  = the semi-vertex angle of the equivalent triangular path.

These quantities are not immediately available; therefore, several intermediate equations must be evaluated, and  $f_v$  is found iteratively. The virtual height  $h'$  is obtained from the equation (Barghausen et al. (1969), equation 5.12)

$$h' = h_0 + y_m f_V/f_c \operatorname{arctanh}(f_V/f_c) , \quad (6)$$

where

$h_0$  = the height of the bottom of the reflecting layer,

$y_m$  = semithickness of the reflecting layer, and

$f_c$  = the critical frequency of the reflecting layer.

The value of  $\phi$  is obtained (Barghausen et al. (1969), equation 5.13) from

$$\tan \phi = \sin(\theta/2) / \left( 1 - \cos\left(\frac{\theta}{2}\right) + \frac{h'}{r_0} \right) , \quad (7)$$

where  $r_0$  = radius of the earth (6371.2 km). Then from

$$h = h_0 + y_m \left( 1 - \sqrt{1 - (f_V/f_c)^2} \right) , \quad (8)$$

the true height of reflection  $h$  is obtained. Finally, the correction factor is determined as follows (Barghausen et al. (1969), equation 5.15):

$$K = 1 / \sqrt{1 - \left( \frac{2(h' - h)}{r_0 + h_0} \right) \tan^2 \phi} . \quad (9)$$

If the takeoff angle and virtual height are desired for a specific frequency  $f_0$ , a suitable initial estimate of  $f_V$ , say  $f_{V1}$  is made, and  $f$  is calculated from (5). Using Newton's iteration method, successive approximations of  $f_V$  are obtained from

$$f_{V(n+1)} = f_{Vn} + (f_0 - f) \frac{\partial f}{\partial f_V} , \quad (10)$$

until the value of  $(f_0 - f)$  is sufficiently accurate. The value of  $h'$  is obtained in the process from (6), and the takeoff angle is then computed by

$$\tan \beta = \left( \cos\left(\frac{\theta}{2}\right) - \frac{r_0}{r_0 + h'} \right) / \sin \frac{\theta}{2} . \quad (11)$$

When the MUF is to be calculated from (5), neither  $f_V$  nor  $f$  is known. However, at the MUF the value of the first derivative of the probing frequency is known to be zero; therefore, the iteration is again started with an estimated value of  $f_V$



and a better estimate is obtained using Newton's iteration method (Barghausen et al. (1969), equation 5.18):

$$f_{v(n+1)} = f_{v_n} - \frac{\partial f / \partial f_v}{\partial^2 f / \partial f_v^2}, \quad (12)$$

until the desired accuracy is attained.

The bending of the ray from a parabolic E layer is incorporated into the calculations of F-layer reflection by an additional iteration procedure. The bending is assumed to take place at both ends of the path. A calculation is made as described for an F-layer reflection without regard to an underlying E layer. Then the bending produced by an E layer is calculated from Barghausen et al. (1969), equation 5.19,

$$\Delta = 2 \left( \frac{y_E}{r_0 + h_E} \right) \left( \frac{\operatorname{arctanh} u}{u} - 1 \right) \tan \alpha, \quad (13)$$

where

$$\begin{aligned} \Delta &= \text{angle in radians by which ray is bent,} \\ y_E &= \text{semithickness of the E layer} = 20 \text{ km,} \\ h_E &= \text{height of maximum electron density of the E layer} = 110 \text{ km,} \\ \alpha &= \text{angle of incidence of the unrefracted ray at the E-layer} \\ &\quad \text{maximum,} \\ \sin \alpha &= r_0 \cos \beta / (r_0 + h_E), \\ u &= foE / (f \cos \alpha), \text{ and} \\ foE &= \text{critical frequency of E layer.} \end{aligned} \quad (14)$$

The bending, in effect, increases the path length and is used to reduce the path length for new calculation of unrefracted rays. The bending calculations are iterated until the desired precision is reached. During this iteration procedure, steps are taken to determine if the E layer does indeed cut off the F-layer propagation.

The ionospheric parameters needed to determine the propagation path geometry (and hence the propagation characteristics) are discussed in Section 2.3.

## 2.2 Signal Strength

The signal power that is available at a receiving antenna terminal can be expressed in logarithmic units as

$$S = P_t + G_t - L - V + G_r \quad , \quad (15)$$

where

$S$  = signal power in dBW,

$P_t$  = transmitted power in dBW,

$L$  = path loss,

$V$  = polarization mismatch loss, and

$G_t, G_r$  = absolute gains of the transmitting and receiving antennas, respectively.

The gain of the transmitting and receiving antennas depends upon the efficiency of the antenna and its directivity with respect to the source. The HF MUFES program contains a subroutine devoted to the determination of the gain of the appropriate transmitting and receiving antennas used in HF skywave circuit simulations. The current air-to-ground program does not compute antenna gains. Antenna gains can be specified by the user if so desired. No polarization mismatch loss is included in the air-to-ground program.

The path loss is determined in exactly the same manner as given in the HF MUFES programs. Three main mechanisms account for almost all the energy losses. Normally the major energy loss is geometrical and is caused by the spreading of the energy over progressively larger areas as the signal propagates from the transmitter. The free-space loss,  $L_{bf}$ , results from the geometrical spreading of energy as the radio wave progresses away from the transmitter and can be expressed as (Barghausen et al. (1969), equation 7.2):

$$L_{bf} = 32.44 + 20 \log_{10} f + 20 \log_{10} D \quad , \quad (16)$$

where  $f$  is wave frequency in MHz and  $D$  is the path length in kilometers.

The second major loss mechanism in radio-wave propagation via the ionosphere is absorption by the ionosphere. Radio waves that are reflected by the E or F2 region lose energy each time they pass through the highly absorbing D region. Nondeviative absorption in the D region is the predominant absorption mechanism at HF, except for radio frequencies in the immediate vicinity of the layer critical frequency. As is the case for HF MUFES, only nondeviative absorption is explicitly calculated by the prediction computer program, as follows (Barghausen et al. (1969), equations 7.4, 7.5):

$$L_i = \frac{286(1 + 0.0087x_n)(1 + 0.005S_{13})W \cos^m(\psi_{12})}{v^2/4\pi^2 + (f + f_H)^2} \cdot \left[ \frac{\cos(0.893\psi)}{\cos(0.893\psi_{12})} \right] n \sec \phi, \text{ (dB)}, \quad (17)$$

where

$$m = 2.25 - 0.32x_n, \quad (18)$$

where  $x_n$  is the geographic latitude in degrees measured positive from the equator,  $S_{13}$  is the smoothed 13-month sunspot number,  $\psi$  is the solar zenith angle in degrees,  $\psi_{12}$  is the solar zenith angle at local noon,  $\phi$  is the angle of incidence of radio ray at 100 km,  $v$  is the collision number ( $v = 20$  at 63 km, and  $v^2/4\pi^2 = 10$ ),  $f_H$  is the gyrofrequency at absorbing height in megahertz,  $W$  is the winter anomaly factor (discussed later), and  $n$  is the number of hops.

At night, the factor

$$(1 + 0.005S_{13}) \cos^m(\psi_{12}) \frac{\cos(0.893\psi)}{\cos(0.893\psi_{12})} \cdot W \quad (19)$$

of equation (17) is set equal to 0.01 to give results that agree with observations. The exponent  $m$  in equation (18) gives results that agree with vertical-incidence absorption measurements at high latitudes, but it yields absorption values that are too large for oblique arctic propagation. Therefore, it is necessary to limit  $m$  in the computer program to  $m=1.3$ . The coefficient  $W$  in equation (17) is an empirical correction for the winter anomaly of ionospheric absorption (Appleton and Piggott, 1954); i.e., in the local winter at medium to high latitudes more absorption is observed than is expected on the basis of simple photoionization theory. In the calculation of ionospheric loss, losses associated with signals reflected from the sporadic-E layer are the same as those estimated for the regular E layer.

The third major loss of radio energy for multiple-hop propagation occurs when the radio wave is reflected from the earth's surface. It is assumed that the incident skywaves are randomly polarized and that the radio energy is distributed equally in the horizontally and vertically polarized fields. The loss caused by reflection is given by Barghausen et al. (1969), equation 7.7:

$$L_g = 10 \log_{10} \left[ \frac{|R_v|^2 + |R_h|^2}{2} \right] \text{ (dB) ,} \quad (20)$$

where  $R_v$  is the reflection coefficient for the vertically polarized wave (electric vector parallel to the plane of incidence), and  $R_h$  is the reflection coefficient for the horizontally polarized wave (electric vector perpendicular to the plane of incidence). The reflection coefficients are defined as the ratios of the electric vector in the reflected wave to the electric vector in the incident wave. Generally, the reflection coefficients are complex numbers, since the refractive index of the earth is a complex quantity. If the earth's magnetic field is neglected, the quantities  $R_v$  and  $R_h$  are given by the Fresnel formulas

$$R_v = \frac{\eta^2 \sin\beta - (\eta^2 - \cos^2\beta)^{\frac{1}{2}}}{\eta^2 \sin\beta + (\eta^2 - \cos^2\beta)^{\frac{1}{2}}} , \quad (21)$$

$$R_h = \frac{\sin\beta - (\eta^2 - \cos^2\beta)^{\frac{1}{2}}}{\sin\beta + (\eta^2 - \cos^2\beta)^{\frac{1}{2}}} , \quad (22)$$

where  $\beta$  is the takeoff angle of the ray above the earth. The quantity  $\eta$  is the complex refractive index. For a time variation of the electric field proportional to  $\exp(j\omega t)$ ,

$$\eta^2 = \epsilon - j 18000\sigma/f , \quad (23)$$

where  $\epsilon$  is the relative dielectric constant of the earth, and  $\sigma$  is the real conductivity of the earth (mhos/meter). The values of  $\epsilon$  and  $\sigma$  used in the HF MUFES prediction program also are used in the air-to-ground program.

As is the case with the HF MUFES program, there is an additional loss term in the air-to-ground program: the excess system loss. This term was employed by Barghausen et al. (1969) in order to account for the day-to-day variations of signals from the monthly median and other losses not explicitly attributed to the mechanisms described above. The excess system loss term in the air-to-ground program is exactly that used in the HF MUFES program.

### 2.3 Ionospheric Structure

The ionospheric structure of the air-to-ground skywave prediction program is the same as that contained within the HF MUFES program. The vertical electron density profile is represented by two parabolas, one each for the E and F2 region of the ionosphere. There is no account taken of the F1 region.

For each parabola, the electron density distribution is specified by the critical frequency, height of maximum ionization, and the semithickness of the region. Sporadic-E ionization is taken into account in the calculation of circuit performance and will be described later in this section.

The E-region critical frequency is determined by use of numerical coefficients of the monthly median foE values valid for the entire globe (Leftin, 1976). The numerical coefficients representing foE were derived from measurements taken during 1958 and 1964. These years were selected for analysis because the data are representative of the high (1958) and low (1964) phases of the sunspot cycle. A linear interpolation procedure is used between the representative data for the high (SSN = 150) and low (SSN = 10) solar activity periods to obtain foE estimates at all other phases of the solar cycle. The height of the maximum electron density of the E region is taken to be constant at 110 km and the semithickness is 20 km (Barghausen et al., 1969).

The F2 region critical frequency is also determined from numerical coefficients valid for the entire globe (Jones et al., 1966). The long-term  $U_{SK}$  coefficients are used primarily for long-range frequency planning and equipment specification and design. The solar activity dependence factor is accounted for by a linear interpolation procedure for any index of sunspot activity from SSN = 0 to SSN = 100. The long-term  $U_{SK}$  coefficients should not be used with sunspot numbers above 150.

The height of the maximum electron density of the F layer is developed in two steps. First, the M(3000)F2 factor is obtained from global numerical maps, and then the true height of the maximum ionization  $h_{max}$  in the layer (Wright and McDuffie, 1960) is calculated on the basis of the following relationship (Shimazaki, 1955):

$$h_{max} = \frac{1490}{M(3000)F2} - 176 \quad . \quad (24)$$

The virtual height of the bottom of the F region is also obtained from numerical maps and is reduced by the retardation ( $\Delta h$ ) in kilometers caused by the underlying E layer (Barghausen et al., 1969, equation 5.9),

$$\Delta h = y_E \left[ Z \log_e \left( \frac{Z+1}{Z-1} \right) - 2 \right] \quad , \quad (25)$$

where

$$Z = 0.834(f_oF2)/f_oE \quad . \quad (26)$$

The results of the calculations are then deemed to be the true heights.

The MUF calculated from parabolic layer theory is based upon median values of the ionospheric characteristics; the probability of a skywave path for this frequency is therefore assumed to be 50 percent. The frequency that would have a 90 percent probability of propagating (FOT) and the frequency that has 10 percent probability (HPF) are obtained by multiplying the MUF by the factors given in the HF MUFES program. For the F2 region, the probability of ionospheric support at a given frequency propagated at a given elevation angle is determined by evaluating the chi-square probability distribution function:

$$q_f = \int_0^{\chi^2} \frac{1}{2^{\xi/2} (\xi/2)} \exp(-z/2) z^{\xi/2 - 1} dz , \quad (27)$$

where

$\chi^2$  = a value related to the operating frequency, and  
 $\xi$  = number of degrees of freedom; describes skewness in the  $\chi^2$  distribution.

It is assumed that any MUF is related to a  $\chi^2$  value by the linear relation,

$$\text{MUF} = C + B \chi^2 , \quad (28)$$

where C and B are constants. The value of the constants C and B and the term  $\xi$  is determined in exactly the same manner as given in the HF MUFES program.

When the regular E region supports propagation, it is assumed to have a probability of 0.99 since the E region is stable and very predictable. When propagation by the regular E region is not possible, the probability that propagation by the sporadic E layer is considered. The median and upper and lower decile values of foEs are obtained from numerical coefficients and converted into values for the oblique path by the secant law relationship. The multiplicative factor,  $\sec \phi$ , is computed as follows:

$$\sec \phi = \frac{1}{\cos\left(\frac{\pi}{2} - \frac{d}{2} - \beta\right)} \quad (29)$$

The probability of sporadic-E propagation is then calculated for the operating frequency from these median and decile values using the chi-squared probability function as given by equation (27). There is no additional loss determined for the partial transparency of the  $E_s$  layer of radio waves.

Most of the ionospheric parameters that are needed to evaluate the equations for the path geometry, the ionospheric loss, and the ionospheric structure and propagation characteristics must be obtained from numerical coefficients. The evaluation of these coefficients is quite lengthy when a large number of skywave circuits are to be simulated. Rather than evaluating the required parameters circuit by circuit, as in the HF MUFES program, the air-to-ground program uses the following procedure.

The area of interest is chosen by assuming that no path is greater than 2000 km and all ionospheric control points fall inside the area. A grid of the ionospheric parameters is generated for a specific sunspot number, month, day, and time of day. The density of the grid is determined by the geographic area selected and accuracy required for the prediction. In the most accurate mode, the results should be exactly those values predicted by program HF MUFES. The control points for a given path are found, and if the control point falls between grid points, each parameter is computed with a two-dimensional interpolation in the grid. The values are used to evaluate the losses and expected performance for that circuit. This method of ionospheric parameter evaluation is significantly faster when the number of circuits exceeds the number of grid points (or when speed in evaluation of a given circuit is required). The speed advantage and the degradation in accuracy will be estimated and discussed in Section 4.

#### 2.4 Noise Parameters

The probability of successful HF transmission depends on the probability that the signal available at the receiving location is above the noise level by a specified amount. The three major types of external noise are galactic, man-made, and atmospheric. In general, these noise types have spectral energy distributions that vary more or less uniformly over the entire high frequency range; however, one type will usually predominate at a given time and place. If each of the two lower noise sources is more than 6 dB below the highest noise power source, they increase the total noise power less than 1 dB and are ignored. However, if one or both of them is within 6 dB of the highest noise source, they make a significant contribution to the total noise power. The amount that must be added to the highest noise power is the same as in the HF MUFES program. If the difference in decibels between the highest noise source and the noise power from a lower noise source is defined as  $\Delta N$ , then the contribution (in dB) to the total noise power from the other sources is as given in Table 1.

Table 1. Contribution in dB to Highest Noise Power from Other Sources

Third Highest Noise Source	Second Highest Noise Source			
	$\Delta N \leq 0.1$	$0.1 < \Delta N \leq 3.0$	$3.0 < \Delta N \leq 6.0$	$N > 6.0$
$\Delta N > 6.0$	3.0	1.8	1.0	0.0
$3.0 < \Delta N \leq 6.0$	3.5	2.4	1.8	
$0.1 < \Delta N \leq 3.0$	4.0	3.0		
$\Delta N \leq 0.1$	4.8			

The median galactic noise is represented by (Lucas and Haydon, 1966)

$$N_g = 165 + 9.555 \log_e \left( \frac{f}{3} \right) \text{ dBW} , \quad (30)$$

where  $N_g$  is the expected median value of the galactic noise power in decibels relative to 1 W in a 1 Hz bandwidth. The temporal variation is estimated at  $\pm 2$  dB (CCIR, 1982c).

The man-made radio noise may arise from any number of sources such as power lines, industrial activity, ignition systems, etc. Man-made noise displays wide geographical and short-term variations (CCIR, 1982d). The median level of man-made noise is based on the same formulation as used by Barghausen et al. (1969), equation 4.2:

$$N_m = N_o + b_N \log_{10} \left( \frac{f}{3} \right) \text{ dBW} , \quad (31)$$

where  $N_m$  is the man-made noise power in decibels below 1 W in a 1 Hz bandwidth, and

$b_N$  is the constant derived from measurements and is given in Table 2.

Values of  $N_o$ ,  $b_N$ , and  $D_u$  or  $D_l$  for three frequency intervals, for four different noise environments, are given in Table 2, where  $D_u$  and  $D_l$  represent the numerical departure of the upper and lower deciles, respectively, of the distribution from the median. An "urban" location is the industrial-business area of large cities; a "suburban" location is one near a large city or within a small town; and a "rural" location is one well removed from all populated areas and chosen to be as free as possible of man-made noise. The upper and lower decile values,  $D_u$  and  $D_l$ , are equidistant from the tabulated values of  $N_o$ , which are the medians (JTAC,



Table 2. Values of Parameters for the Man-Made Noise Models

Man-made Noise Model	Frequency Interval (MHz)	$N_o$ (dBW)	$b_N$	$D_\mu = D_\ell$ (dB)
Urban	$f \leq 10$	-136.5	-27.1	4.2
	$10 < f < 20$	-150.2	- 1.0	5.8
	$f \geq 20$	-132.5	-22.5	7.4
Suburban	$f \leq 10$	-148.6	-29.4	5.8
	$10 < f < 20$	-167.5	+ 6.6	8.8
	$f \geq 20$	-142.2	-24.0	11.8
Rural	$f \leq 10$	-165.6	-34.3	10.0
	$10 < f < 20$	-196.5	+24.9	7.1
	$f \geq 10$	-155.4	-25.0	4.2
User Designated	$f \leq 20$	$N_{user}$	-29.3	5.8
	$10 < f < 20$	$N_{user} -18.9$	+ 6.6	8.8
	$f \geq 20$	$N_{user} +6.4$	-24.0	11.8

1968). The estimated uncertainties in predicting the median and deciles are 3 dB and 1.5 dB, respectively.

The man-made noise used in this prediction program does not include man-made noise generated by aircraft. Further, there is no altitude variation in either man-made noise or atmospheric noise in the program. These limitations could be significant in assessing reception of signals in elevated platforms.

Atmospheric noise is the most erratic of the three major types of noise. It is generally characterized by short pulses with random recurrence superimposed upon a background of random noise (Crichlow et al., 1955). Averaging these short pulses of noise power over several minutes yields average values that are nearly constant during a given hour. The variations seldom exceed  $\pm 2$  dB, except during sunrise or sunset periods and when local thunderstorms are present. Worldwide maps published in CCIR Report 322, representing the median of hourly medians of atmospheric noise at 1 MHz within 4-hour time blocks for the four (3-month) seasons of the year, are used as the basis for estimating this noise at any given receiving location. Levels of atmospheric noise for other frequencies and their associated distributions about the medians are available for each time block and season.

The maps in CCIR Report 322 were used to generate, by means of a least-squares fit based on Fourier analysis, numerical coefficients representing the worldwide distribution of atmospheric noise (Lucas and Harper, 1965) as a function of geographic location. The curves of frequency dependence and variability of the radio noise were generated from a power series or least-squares fit. The numerical maps and complete listings of the numerical coefficients used in the prediction program are given in NBS Technical Note 318 (Lucas and Harper, 1965). The numerical coefficients in latitude, longitude, and local mean time at the receiving location give the median atmospheric noise power in decibels above  $k T_0 b$ , at 1 MHz for each time block and season. The value of  $k$  (Boltzmann's constant) is  $1.38 \times 10^{-23}$  joules per degree Kelvin, the reference temperature is  $288^\circ\text{K}$ , and  $b$  is the bandwidth in Hz. Noise values for other frequencies and their distributions are evaluated from numerical arrays derived from the frequency curves for each time block and season. Because evaluating the coefficients for the atmospheric noise each time that the performance characteristics of a given HF skywave circuit is required would take too long, the atmospheric noise parameters are precalculated for a given universal time at the same grid points used for the ionospheric parameters. Then, during circuit evaluation, atmospheric noise is interpolated from the precalculated values. The noise parameters that are frequency dependent, such as the man-made noise, are not precalculated.

### 3. GROUNDWAVE FIELD STRENGTH CALCULATIONS

When the transmitter and receiver are not widely separated (less than 300 km during the day and less than 100 km during the night), the groundwave may provide a better communications mode than the skywave. This is especially true when at least one terminal is elevated. The term groundwave is used to include the surface wave that diffracts around the curved earth, the direct line-of-sight space wave, and the ground-reflected wave. The direct wave is assumed to suffer attenuation due only to spreading of the wave as it propagates.

The basis of the calculations of the signal strength of the groundwave in the air-to-ground program is the work of Berry (L. A. Berry, User's Guide to Low-Frequency Radio Coverage Programs, OT Technical Memorandum 78-247, January 1978). The model used is applicable to predicting groundwave signal strength for smooth, homogeneous paths (GWSNR in the Berry reference). The field strength is calculated with one of three different formulas, depending on the geometry of the transmitter and receiver locations, the ground constants, and the radio frequency.

If both transmitter and receiver are near the earth (in wavelengths), then the radio wave propagates as a surface wave. For short path lengths, it is valid to assume that the earth is flat. For these conditions, use is made of the flat earth attenuation function (Wait, 1964),

$$E(d) = \frac{9.487\sqrt{P_E}}{d} A(z) \quad , \quad \text{V/m} \quad , \quad (32)$$

where  $P_E$  is the effective radiated power in watts,  $d$  is the distance in kilometers, and  $A(z)$  is the flat earth attenuation function.

$$A(z) = (1 - R_0 \delta e^{z^2} \text{erfc}(z)) \quad , \quad (33)$$

where  $\delta$  is the surface impedance of the ground,

$$\delta = \begin{cases} \sqrt{\eta^2 - 1} / \eta^2 & \text{for vertical polarization,} \\ \sqrt{\eta^2 - 1} & \text{for horizontal polarization,} \end{cases} \quad (34)$$

and  $\eta^2$  is given in (23).

$$R_0 = e^{j\pi/4} \sqrt{\pi\gamma D/2} \quad , \quad (35)$$

$$D = \sqrt{d^2 + (h_1 - h_2)^2} \quad , \quad (36)$$

where  $h_1$  and  $h_2$  are the heights of the transmitter and receiver,  $\gamma = 2\pi/\lambda$  where  $\lambda$  is the free space wavelength,

$$z = e^{j\pi/4} \sqrt{\frac{\gamma D}{2}} \delta \left(1 + \frac{h_1 + h_2}{\delta D}\right) \quad , \quad (37)$$

and  $\text{erfc}(z)$  is the complementary error function (Abramowitz and Stegun, 1964).

If the transmitter and receiver are high enough that one is well above the radio horizon when viewed from the other, the field is calculated using geometrical optics. The geometrical quantities are defined in Figure 1.

$$E = 9.487 \sqrt{P_E} \frac{e^{-j\gamma(D-d)}}{2D} (1 + R_g e^{-i\gamma(D_1 + D_2 - D)}) \quad , \quad (38)$$

where  $R_g$  is the appropriate ground reflection coefficient,  $R_V$  or  $R_h$  (21, 22), and

$$D = \sqrt{(2\theta_0^2 + 2\theta_0(h_1 + h_2))(1 - \cos \theta) + h_1^2 + h_2^2 - 2h_1 h_2 \cos \theta} \quad . \quad (39)$$

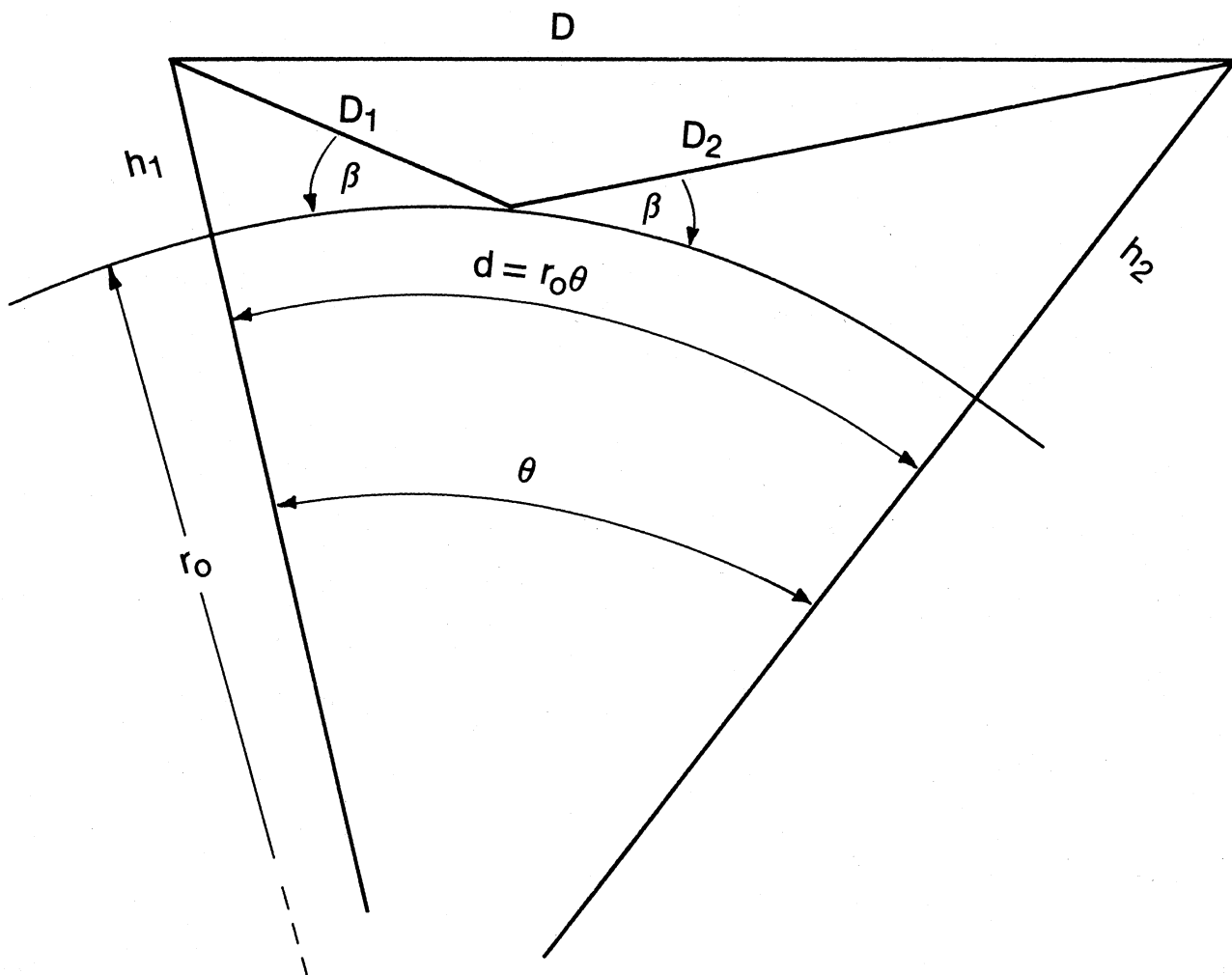


Figure 1. Geometrical representation for groundwave calculations.

Closed form solutions for  $D_1$ ,  $D_2$ , and  $\beta$  are not possible, but an iteration using the following relations will converge. Let

$$D_i = \sqrt{r_0^2 \sin^2 \beta + A_i} - a \sin \beta, \quad i = 1, 2, \quad (40)$$

where

$$A_i = 2r_0 h_i + h_i^2. \quad (41)$$

Using the law of cosines, it can be shown that

$$(D_1 + D_2)^2 - 4D_1D_2 \sin^2 \beta - D^2 = 0. \quad (42)$$

Perform the following iteration:

- (i) For an  $n$ -th approximation to  $\sin \beta$ ,  $S_n$ , compute  $D_1$  and  $D_2$  using (40).
- (ii) Compute  $e_n = (D_1 + D_2)^2 - 4D_1D_2 \sin^2 \beta - D^2$ . (43)

If  $e_n$  is sufficiently small, (42) is satisfied and iteration has converged. Otherwise,

$$(iii) \quad S_{n+1} = S_n + e_n \left( \frac{S_n - S_{n-1}}{e_n - e_{n-1}} \right). \quad (44)$$

(This assumes that  $e_n$  is an approximately linear function of  $S_n$ .) Return to (i) and do another iteration.

For small  $\beta$ ,  $D_1 + D_2 \sim D$ , so that computing  $D_1 + D_2$  directly results in unacceptable round-off error. To avoid this loss of precision, use

$$D_1 + D_2 - D = \frac{4 D_1 D_2 \sin^2 \beta}{D_1 + D_2 + D}. \quad (45)$$

When the receiving antenna is near the radio horizon of the transmitting antenna, the field is difficult to compute because diffraction effects are important, but the direct ray is also present. In this region, it is necessary to numerically integrate the full-wave theory integral shown below:

$$E = 9.487 P_E \sqrt{\frac{v}{12 \sin \theta}} \frac{e^{j3\pi/4}}{r_0} \int_{\Gamma} e^{-j\gamma t} F_I(Q, t) dt, \quad (46)$$

where

$$v = (\gamma r_0/2)^{1/3}, \quad x = v\theta, \quad \text{and } Q = -jv\delta \quad . \quad (47)$$

The contour  $\Gamma$  comes from  $\infty e^{-j\pi/4}$  on a straight line with a slope of  $-1$  to  $(\text{Re}(t_0) - j/2 \text{Im}(t_0))$  and then proceeds on a straight line with slope  $+1$  to  $\infty e^{-j3\pi/4}$ .  $t_0$  is the first pole of  $F_I(Q,t)$ .  $\text{Re}$  designates the "real part of" and  $\text{Im}$  designates the "imaginary part of."

$$F_I(Q,t) = \frac{H_1(h_1) H_2(h_2)}{\frac{W_1'(t)}{W_1(t)} - Q} \quad . \quad (48)$$

The height gain functions are

$$H_1(h) = \frac{W_1(t-y)}{W_1(t)} \quad (49)$$

and

$$H_2(h) = -.5j W_2(t-y)[W_1'(t) - QW_1(t)] \\ - W_1(t-y)[W_2'(t) - QW_2(t)] \quad , \quad (50)$$

where  $y = \gamma h/v$ . Note that  $H_1(0) = H_2(0) = 1$ . The functions  $W_n(t)$  are Airy functions (Wait, 1964) which satisfy

$$W_n''(t) = tW_n(t) \quad . \quad (51)$$

The computations of the groundwave signal strength that follow from the preceding equations are time-consuming. Therefore, it was decided to seek a faster procedure for determination of the groundwave signal strength. The method adopted relies upon results of calculations of groundwave signal loss that are plotted as families of curves that are then represented by a set of numerical coefficients. The coefficients for a given circuit are determined by interpolating between the input coefficients, and then evaluating the simple formulas given below.

Specifically, the determination of the coefficients is as follows: Using program GWSNR, a family of curves of loss as a function of frequency and distance was generated and plotted for each of the following antenna height combinations:

(1 m, 1 m), (1 m, 5 m), (1 m, 10 m), (1 m, 50 m), ... (1 m, 50 km)  
 (5 m, 5 m), (5 m, 10 m), (5 m, 50 m), (5 m, 100 m), ... (5 m, 50 km)  
 .  
 .  
 .  
 (10 km, 10 km), (10 km, 50 km)  
 (50 km, 50 km) .

Examples for heights (1 m, 1 m) and (1 m, 10 km) are given in Figure 2. The permittivity and ground conductivity were fixed at 10.0 and 0.005 mho/m. The antenna polarity was assumed vertical. For each antenna combination, two equations were fitted to the 2 MHz through 30 MHz curve. The equations were of the type

$$y = a_0 + a_1 \log (d - d_1) \quad (52)$$

$$y = a_{00} + a_{11} (d - d_2) , \quad (53)$$

where  $d$  is the great circle distance,  $d_1$  is the distance at which the groundwave loss is greater than the free space loss, and  $d_2 = d_1 + 110$  km.

When  $d$  is less than  $d_1$ , the loss is calculated as

$$\text{Loss} = 32.45 + 20.0 \log_{10} (d \cdot f) . \quad (54)$$

When  $d$  is greater than  $d_1$ , the loss is calculated as

$$\text{Loss} = [32.45 + 20.0 \log (d \cdot f)] + [a_0 + a_1 \log(d - d_1)] . \quad (55)$$

When  $d$  is greater than  $d_1 + 110$  km, the loss is calculated as

$$\text{Loss} = [32.45 + 20.0 \log (d \cdot f)] + [a_{00} + a_{11}(d - d_2)] . \quad (56)$$

The  $a_{11}$  coefficient does not vary with height until one of the antenna heights exceeds 5 km. When the 5-km height is exceeded, a constant factor is subtracted from coefficient  $a_{11}$  before calculation of the equation. The  $a_0$ ,  $a_1$ , and  $a_{00}$  coefficients vary both with frequency and antenna height, and therefore must be interpolated in two dimensions. After analyses of all the height combinations and frequency levels, the sets of coefficients to be used for interpolation are the following:

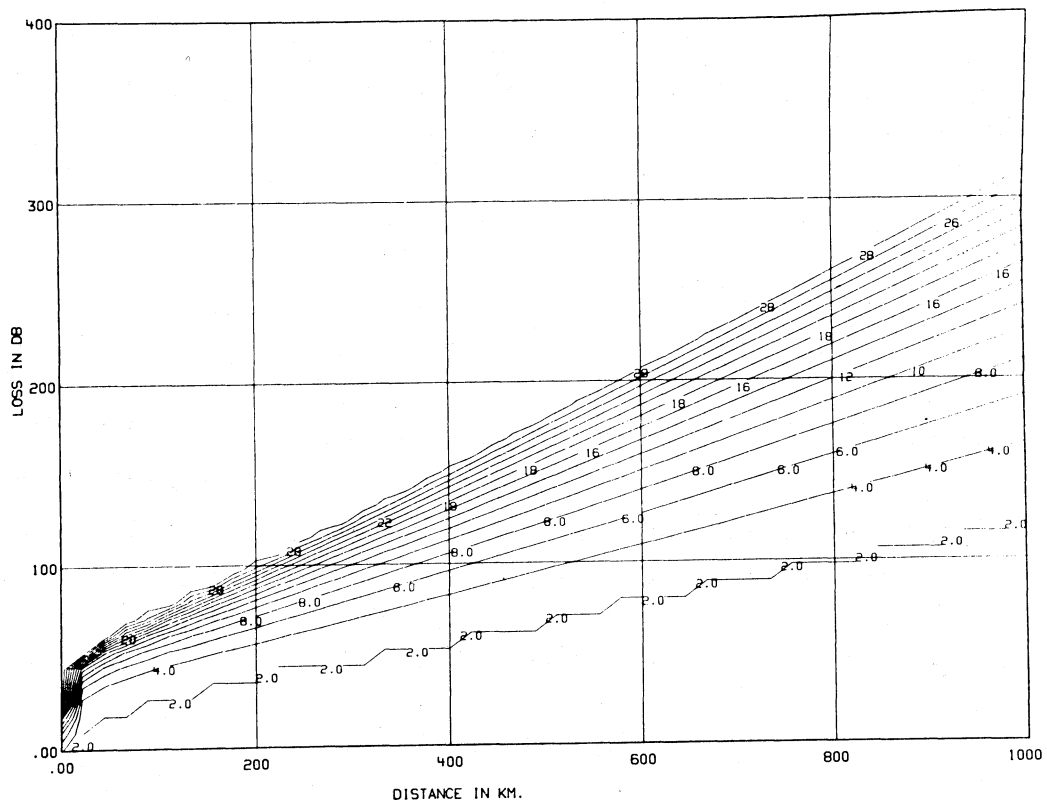


Figure 2a. Groundwave loss (in dB) for antenna heights of 1 m, parametric in frequency (2 to 30 MHz), for transmitter and receiver.

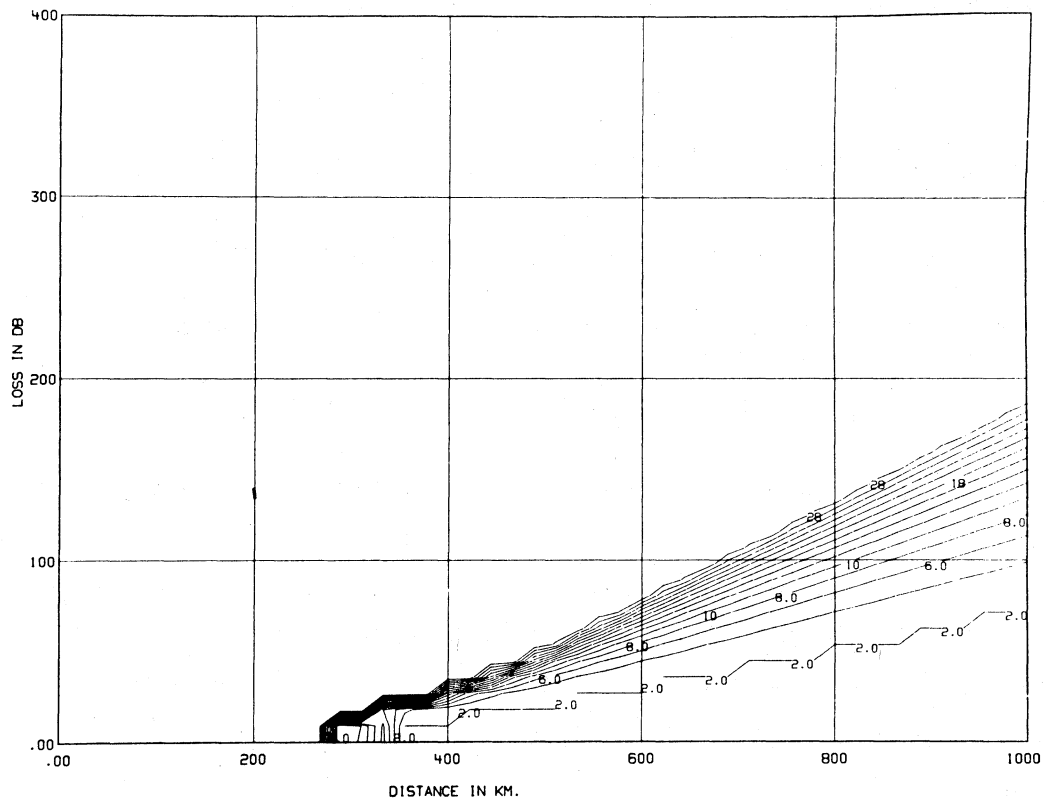


Figure 2b. Groundwave loss (in dB), parametric in frequency (2 to 30 MHz), for antenna heights of 1 m for the transmitter and 10 km for the receiver.



$d_1$  for all height combinations and frequencies 2 MHz to 30 MHz,  
 $a_{11}$  for each frequency 2 MHz to 30 MHz,  
 $a_{00}$  for all height combinations at frequencies 2 MHz and 30 MHz, and  
 $a_0$  for all height combinations at frequencies 2 MHz and 30 MHz.

The final sets of distances and coefficients are used as constant tables in subroutine GWAVE. When subroutine GWAVE is executed, the inputs are antenna heights, frequency, and path length. The coefficients are interpolated in these three dimensions, and the output is ground loss in dB. The angle of arrival of the groundwave is calculated as the direct wave when the antennas are within line-of-sight and as the horizontal angle when the antennas are not within line-of-sight. An error analysis of this model will be presented in Section 4.

#### 4. CIRCUIT CALCULATIONS USING THE AIR-TO-GROUND HF PROPAGATION MODEL

In this section the air-to-ground HF propagation model is used to calculate circuit parameters for a number of different paths contained within Europe. This section provides a description of the input required for the prediction program and the output generated. Also a discussion of the accuracy and speed of the program is presented.

In Figure 3, two ground-to-air circuits are shown in a schematic fashion. The letter "T" represents the location of the transmitter, and there are two receiving aircraft pictured. The great circle paths for a short propagation circuit and a long circuit are shown as the dashed lines. The letter "A" is used to indicate the path mid-point for both circuits. This is the location at which the E and F layer parameters are evaluated. The solid line adjacent to the great circle path for the short circuit represents the groundwave. For the long path, the points B and C represent the penetration of the radiowave through the lower ionosphere. This is the location where the ionospheric loss is evaluated for the up-going (B) and down-coming (C) positions of the path. The points "D" and "E" indicate the points of reflection if two ionospheric reflections were to occur along the longer propagation path.

In the discussions that follow, reference will be made to a number of HF circuits that were simulated for this study. The particulars of the circuits are given in Table 3.

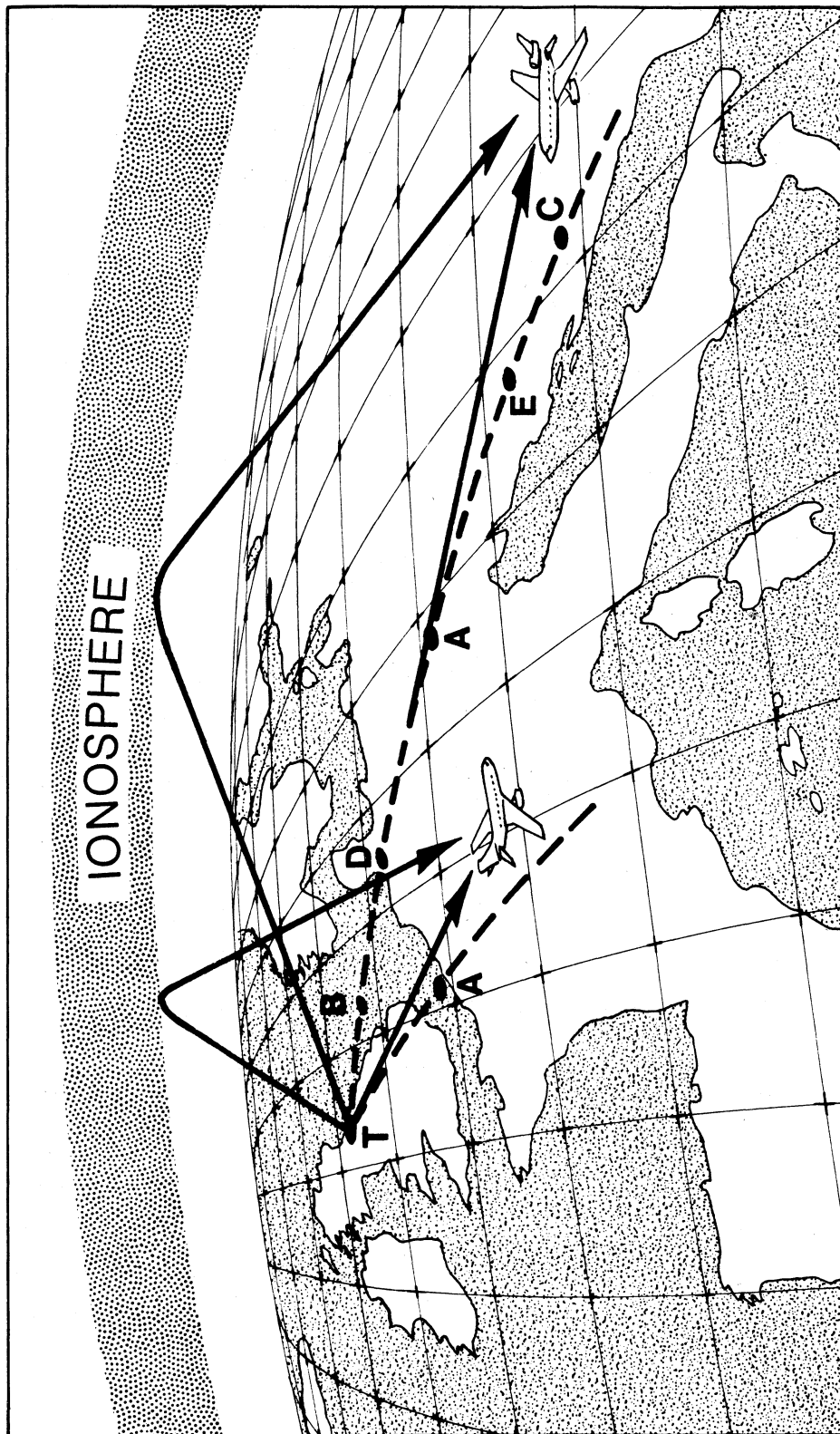


Figure 3. Conceptual air-to-ground HF skywave and groundwave circuits.

Table 3. Characteristics of Simulated Circuits for Frequencies  
3, 5, 8, 11, 15, 18, 21, and 26 MHz

Circuit Number	Transmitter Location*	Receiver Location	Transmitter Power (watts)	Receiver Height (km)
1	45°N,5°E	45°N,10°E	100	0
2	45°N,5°E	45°N,15°E	100	0
3	45°N,5°E	45°N,20°E	500	0
4	45°N,5°E	45°N,25°E	500	0
5	45°N,5°E	45°N,30°E	500	0
6	55°N,15°E	50°N,15°E	100	0
7	55°N,15°E	45°N,15°E	100	0
8	55°N,15°E	40°N,15°E	100	0
9	55°N,15°E**	35°N,15°E	500	0
10	55°N,15°E**	30°N,15°E	500	0
11	45°N,10°E	45°N,11°E	100	10
12	45°N,10°E	45°N,12°E	100	10
13	45°N,10°E	45°N,13°E	100	10
14	45°N,10°E	45°N,14°E	100	10
15	45°N,10°E	45°N,15°E	100	10
16	45°N,10°E	45°N,16°E	200	10
17	45°N,10°E	45°N,18°E	200	10
18	45°N,10°E	45°N,20°E	200	10
19	45°N,10°E	45°N,22°E	200	10

\* All transmitters are on the surface of the earth.

\*\* Path length greater than 2000 km; results not included in summary in Table 6.

#### 4.1 Program Input and Output

The following parameters must be specified by the user in order to compute HF propagation parameters with the air-to-ground model:

- (1) Location of transmitters and receivers.
- (2) Time for which calculations are to be performed--month and hour.
- (3) Solar activity conditions.
- (4) Frequency for which calculations are to be performed.
- (5) Transmitter power (or powers).
- (6) Minimum useful elevation angle at the transmitters and/or receivers.
- (7) Man-made noise level as indicated in Table 2.
- (8) Required signal level above the noise in order to assure proper operation of the circuit.
- (9) Required reliability (discussed below).
- (10) Maximum tolerable time-delay difference between two modes. This time-delay difference is used to determine the likelihood of multipath interference. The quantities used depend on the quality of reception (reliability) expected for the circuit.
- (11) Ground conductivity and ground constant if the default values ( $\sigma = 0.005$  mho/m and  $\epsilon = 15$ ) are not desired.

The circuit reliability is based upon the monthly median estimates of propagation parameters and their distributions and represents the fraction of days in the month at the given hour that successful communication is expected at a specific operating frequency. The primary factor in determining the circuit reliability is the median  $S/N_0$  ratio. A minimum required  $S/N_0$  ratio is associated with the desired grade of service. This ratio depends upon many factors, such as modulation index, signalling rates and codes, and includes effects of fading, error-correcting schemes, optimum modulation and detection techniques, and diversity schemes.

Mathematically, the circuit reliability can be expressed as a dimensionless quantity  $R$  given by

$$R = qp/100 \quad , \quad (57)$$

where  $R$ ,  $q$ ,  $p$  are expressed as percentages;  $q$  is the skywave availability defined as the percentage probability that radio signals can propagate at a given hour over a given skywave path; and  $p$  is the percentage probability that the mean received signal-to-noise ratio is above the required signal-to-noise ratio.

In the prediction program, the two factors  $q$ ,  $p$  do not need to be associated with the same propagation mode. The program selects the lowest loss of all the likely modes and combines this with the highest likelihood of ionospheric support to calculate the circuit reliability. A detailed discussion of the effect of signal-to-noise on reliability has been most recently described by Maslin (1978).

As was indicated in Section 2, for each hour of time that is specified, a latitude-longitude grid is generated in a subroutine named MAPPR. A number of parameters are evaluated at the grid points. These parameters are listed in Table 4. Table 5 provides a listing of the subroutine HF $\check{S}$ SKGD, which controls the input and output for the calculations of path parameters and statistics.

The output of the air-to-ground computer program can be varied to satisfy the requirements of the user. The complete output is shown in Figure 4 for the case of a circuit with a 100 W transmitter at 45°N, 5°E on a frequency of 11 MHz and receiver on the ground at 45°N, 10°E. Shown are the various parameters involved in the system performance predictions by tabulating the geometry used for the ray paths, the ionosphere characteristics involved, and the expected performance of each mode for selected times and frequencies.

The first line contains the universal time, month, day, year, and the solar activity level as indicated by the 12-month running average Zurich sunspot number. The second and third lines contain the coordinates and heights of the transmitter and receiver, the azimuthal bearings (in degrees east of north) of the receiver from the transmitter and vice versa, and the length of the circuit in kilometers. The fourth line contains the frequency, the transmitter power, the hourly median signal-to-noise ratio required to provide the type of service needed, the type of man-made noise at the receiver location, the required percent reliability, the multipath power tolerance in decibel, and the multipath delay tolerance in milliseconds.

The next section of the figure provides the information concerning the data representative of the skywave reflection area. The following are tabulated:

- DIST FM TX - the distance in kilometers along the great-circle path from the transmitter toward the receiver to each reflection area where the ionosphere is sampled,
- LATITUDE - the latitude in degrees of the sample location--southern latitudes are indicated by a (-) preceding the degrees,
- LONGITUDE - the longitude of the sample location--east longitudes are indicated by a (-) preceding the degrees,
- GEOM LAT - the geomagnetic latitude,
- TIME HOURS - the local time at the sample location,

Table 4. Input-Output Parameter Description for Subroutine MAPPR

SUBROUTINE MAPPR (SSN, GMT, MONDAY, GLAT, GLONG, GRD)

Input:

SSN = 12 month smoothed Zurich sunspot number

GMT = universal time

MONDAY = month and day

GLAT(1) = southern-most geographic latitude,  
+ = north, - = south

GLAT(2) = northern-most geographic latitude,  
+ = north, - = south

GLONG(1) = western-most longitude,  
+ = west, - = east

GLONG(2) = eastern-most longitude,  
+ = west, - = east

Output:

GRD (1) = latitude of the southern-most point in the grid (radians)

(2) = latitude of the northern-most point in the grid (radians)

(3) = step size between latitude points (radians)

(4) = longitude of the eastern-most point of the grid (radians)

(5) = longitude of the western-most point of the grid (radians)

(6) = step size between longitude points (radians)

(7) = universal time for this grid

(8) = 12-month smoothed mean sunspot number for this grid

(9) = month and day for this grid (MMDD)

(10) = 100 km gyrofrequency for the first grid point

(11) = FoE for first grid point

(12) = FoEs upper decile for first grid point

(13) = FoEs median for first grid point

(14) = FoEs lower decile for first grid point

(15) = HoF2 for first grid point

(16) = FoF2 for first grid point

(17) = M3000 for first grid point

(18) = 300 km gyrofrequency for first grid point

(19) = absorption for the first grid point

(20) = intercept of regression on K factor (from PMUFG)

(21) = slope of regression on K factor (from PMUFG)

(22) = noise for the first grid point (from WOMAP)

(23) = ground constant for the first grid point (from WOMAP)

(24) = FOT factor for first grid point (from F2DIS)

(25) = HPF factor for first grid point (from F2DIS)

(26) = excess system loss for first grid point (from SYSSY)

(27) = upper standard deviation of excess system loss (from SYSSY)

Table 4. Input-Output Parameters Description for Subroutine MAPPR  
(continued)

GRD (28)	=	lower standard deviation of excess system loss (from SYSSY)
(29)	=	error in excess system loss for the first grid point (from SYSSY)
(30)	=	upper standard deviation of error in excess system loss (from SYSSY)
(31)	=	lower standard deviation of error in excess system loss (from SYSSY)
(32)	=	100 km gyrofrequency for second point in the grid
.		
.		
.		
GRD (54)	=	100 km gyrofrequency for third point in grid
.		
.		
.		
GRD (9 + 22 x No. of grid points)	=	lower standard deviation of the error in excess system loss for the last grid point (from SYSSY)
GRD (10 + 22 x No. of grid points)	=	first atmospheric noise coefficient
.		
.		
.		
GRD (468 + 22 x No. of grid points)	=	last atmospheric noise coefficient

MAPPR uses the standard HF MUFES data tape, or data file, to make parameter predictions.

Table 5. Input-Output Parameter Description for Subroutine HFSKGD

SUBROUTINE HFSKGD (PPRAM, NPRAM, FPIN, FPOT)

A routine to calculate path parameters and statistics for transmitter to receiver circuit.

Input:

Path Parameters

- PPRAM (1) = power to transmitter in kW
- (2) = frequency in MHz
- (3) = transmitter latitude in degrees
- (4) = transmitter longitude in degrees
- (5) = height of transmitter in km
- (6) = receiver latitude in degrees
- (7) = receiver longitude in degrees
- (8) = height of receiver in km

System Parameters

- NPRAM (1) = required signal-to-noise ratio in dB
- (2) = man-made noise:
  - 1 = urban
  - 2 = suburban
  - 3 = rural
  - >3 = user designated
- (3) = required circuit reliability
- (4) = minimum difference in signal power in dB for multipath
- (5) = maximum difference in time delay in ms for multipath

- FPIN = input grid of ionospheric characteristics and the statistics associated with them

Output:

- FPOT (1) = mean path loss (dB) for skywave
- (2) = upper decile of path loss
- (3) = lower decile of path loss
- (4) = mode indicator
- (5) = angle of arrival skywave
- (6) = angle of arrival direct
- (7) = noise level
- (8) = circuit reliability
- (9) = time delay in ms
- (10) = multipath probability
- (11) = groundwave loss in dB

All control points must remain within the grid of latitude and longitude that was used to generate FPIN.



- ABSORP FAC - an index of ionospheric absorption depending primarily upon the solar zenith angle,
- E LAYER CR - the maximum frequency in megahertz returned from the E region at vertical incidence,
- F LAYER BT - the height of the lower part of the F region in kilometers,
- HT OF F MAX- the height of the maximum ionization of the F region in kilometers,
- GYRO FREQ - the gyrofrequency in megahertz at 100 km,
- F LAYER CT - the critical frequency of the F region in megahertz,
- ES UP DEC - the upper decile of the frequency supported by sporadic E at vertical incidence,
- ES MED VAL - the vertical incident monthly median frequency supported by sporadic E,
- ES LOW DEC - the lower decile of sporadic E,
- EX SYS STS - an estimate of propagation losses in decibels not specifically included in the computations, and
- ANO STATIS - an estimate of the noise statistics in decibels.

The next part of the figure tabulates parameters associated with the expected modes of propagation: (E MODES), (F MODES), and (E F MODES). For each mode the tabulation includes:

- NO OF HOPS - the number of ionospheric reflections considered for each mode,
- TK OFF ANG - the vertical angle of departure and arrival corresponding to the number of hops,
- VIRTUAL HT - the apparent height of ionospheric reflection for the mode,
- TM DLY MS - the propagation time for the mode in milliseconds
- SKY WV LOS - a loss in decibels due to the free-space spreading of the transmitted energy as it travels via the skywave,
- ABSRP LOSS - loss in decibels due to absorption in the lower ionosphere,
- GRD REF LS - a loss in decibels due to ground reflection when multiple ionosphere reflections are involved,
- TRNSMSN LS - a summation of the above losses (including the "excess system loss"),
- FIELD STRN - the monthly median strength of the signal at the receiver in decibels relative to  $1 \mu\text{V/m}$ ,
- SIG POWER - an estimate of the power available at the receiver in decibels referred to 1 W,
- S/N IN DB - total signal power relative to noise power in a 1 Hz bandwidth at the receiver input,

- FRACT DAYS - the percentage of days within the month that this mode of propagation is expected,
- FRACT S/N - the fraction of days that the required S/N ratio is expected to be equalled or exceeded,
- RELIABILITY- the percentage of days within the month that the required S/N ratio is expected to be equalled or exceeded and the mode is expected to be supported by the ionosphere [the product of (FRACT DAYS) and (FRACT S/N)], and
- SERV PROB - the likelihood that the circuit reliability requirement will be met.

The bottom of the figure provides a listing of the most important characteristics for the frequency being calculated. The third from the last line shows the skywave mode with the least loss, reliability, the multipath probability for that mode, the path loss in decibels, the upper and lower decile of the path loss, and the time delay in milliseconds for the mode. The next to the last line shows the angle of arrival of the mode with the least loss, the noise level at the receiver location, and the circuit reliability. The last line shows the angle of arrival of the direct wave and the loss in decibels of the groundwave mode.

If the reader requires further explanation of the output parameters, reference should be made to the work of Haydon et al. (1976).

#### 4.2 Air-to-ground Program Speed and Accuracy

Figures 4 through 22 show the results of calculations for all the circuits listed in Table 3. The calculations are for a universal time of 1100 hours for solar activity conditions appropriate for December 1982. For each of the circuits, calculations were performed for the frequencies listed in Table 3, but only 11-MHz results are shown. The path lengths range from 79 km to 2780 km.

The air-to-ground computer program was designed to calculate circuit parameters for a large number of frequencies and path lengths in a given area for a given time. It takes a little over 4 s on the Boulder Laboratory CYBER 750 to generate the values of all the parameters on the grid using subroutine MAPPR. Once the grid is specified, it takes about 60 ms to compute the skywave propagation characteristics for each frequency specified. In order to calculate the same parameters using the HFUFES program, the ionospheric and noise parameters would have to be evaluated each time a different frequency and circuit length are specified. Thus the more circuits and frequencies to be calculated, the faster the air-to-ground program is relative to HFUFES. Subroutine HFSKGD calculates skywave parameters about six times faster than HFUFES. The calculations of the groundwave loss in the air-to-

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTR	45.0	5.0	1.0	88.2	393.1
RECEIVER	45.0	10.0	1.0	271.8	393.1

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	196.542	98.271	294.813	196.542	196.542	
LATITUDE	45.027	45.020	45.020	45.027	45.027	
LONGITUDE	-7.500	-6.250	-8.750	-7.500	-7.500	
GEOM. LAT.	46.563	46.806	46.308	46.563	46.563	
TIME HOURS	11.500	0.000	0.000	0.000	0.000	
ABSORP FAC	.799	0.000	0.000	0.000	0.000	
E LAYER CR	2.990	0.000	0.000	0.000	0.000	
F LAYER RT	221.349	0.000	0.000	0.000	0.000	
HT OF FMAX	272.919	0.000	0.000	0.000	0.000	
GYRD FREQ.	1.284	0.000	0.000	0.000	0.000	
F LAYER CT	10.089	0.000	0.000	0.000	0.000	
FS UP DEC	3.738	0.000	0.000	0.000	0.000	
FS MED VAL	3.219	0.000	0.000	0.000	0.000	
ES LOW DEC	2.647	0.000	0.000	0.000	0.000	
EX SYS STS	9.000	6.835	4.311	3.062	2.062	1.062
AND STATIS	-174.848	8.034	6.518	3.392	2.301	5.564

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	
TK OFF ANG	0.000	0.000	54.452	74.938	80.293	0.000	0.000	
VIRTUAL HT	0.000	0.000	289.052	386.830	406.485	0.000	0.000	
TM DLY MS.	0.000	0.000	2.357	5.352	8.272	0.000	0.000	
SKY WV LOSS	1000.000	1000.000	110.262	117.384	121.167	1000.000	1000.000	
ABSRP LOSS	1000.000	1000.000	2.433	4.127	6.069	1000.000	1000.000	
GND REF LS	1000.000	1000.000	0.000	.462	.927	1000.000	1000.000	
TRNSMSN LS	1000.000	1000.000	121.695	130.973	137.162	1000.000	1000.000	
FIELD STRN	-1000.000	-1000.000	26.333	17.055	10.866	-1000.000	-1000.000	
SIG POWER	-1000.000	-1000.000	-101.695	-110.973	-117.162	-1000.000	-1000.000	
S/N IN DB.	-1000.000	-1000.000	61.583	52.305	46.116	-1000.000	-1000.000	
FRACT DAYS	0.000	0.000	.580	.496	.495	0.000	0.000	
FRACT S/N	0.000	0.000	.762	.376	.135	0.000	0.000	
RELIABILITY	0.000	0.000	.443	.187	.067	0.000	0.000	
SERV. PROB	0.000	0.000	.086	.001	.000	0.000	0.000	

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=112.9 UD=108.9 LD=117.0 TIM DLY MS= 2.357  
 ANGLE OF ARRIVAL SKYWAVE= 54.5 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .76  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 218.3

Figure 4. Output of air/ground model for circuit (1) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTR	45.0	5.0	1.0	86.5	785.8
RECEIVER	45.0	15.0	1.0	273.5	785.8

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	392.896	196.448	589.344	392.896	392.896	
LATITUDE	45.109	45.082	45.092	45.109	45.109	
LONGITUDE	-10.000	-7.498	-12.502	-10.000	-10.000	
GEOM. LAT.	46.144	46.616	45.619	46.144	46.144	
TIME HOURS	11.667	0.000	0.000	0.000	0.000	
ABSORP FAC	.803	0.000	0.000	0.000	0.000	
E LAYER CP	2.995	0.000	0.000	0.000	0.000	
F LAYER BT	221.545	0.000	0.000	0.000	0.000	
HT OF FMAX	274.917	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.288	0.000	0.000	0.000	0.000	
F LAYER CT	10.150	0.000	0.000	0.000	0.000	
ES UP DEC	3.750	0.000	0.000	0.000	0.000	
ES MED VAL	3.243	0.000	0.000	0.000	0.000	
ES LOW DEC	2.655	0.000	0.000	0.000	0.000	
EX SYS STS	9.000	6.556	4.111	3.022	2.022	1.022
AND STATIS	-174.715	8.045	6.526	3.427	2.278	5.581

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	0.000	0.000	29.792	54.577	69.311	0.000	0.000	0.000
VIRTUAL HT	0.000	0.000	241.286	290.291	366.860	0.000	0.000	0.000
TM DLY MS.	0.000	0.000	3.133	4.727	7.846	0.000	0.000	0.000
SKY WV LOS	1000.000	1000.000	112.733	116.307	120.707	1000.000	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	3.859	4.883	6.416	1000.000	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	.647	1.345	1000.000	1000.000	1000.000
TRNSMSN LS	1000.000	1000.000	125.592	130.837	137.468	1000.000	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	22.436	17.191	10.560	-1000.000	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-105.592	-110.837	-117.468	-1000.000	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	57.677	52.432	45.801	-1000.000	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.994	.586	.499	0.000	0.000	0.000
FRACT S/N	0.000	0.000	.620	.380	.122	0.000	0.000	0.000
RELIABILTY	0.000	0.000	.616	.223	.061	0.000	0.000	0.000
SERV. PROB	0.000	0.000	.036	.001	.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=117.2 UD=113.2 LD=121.2 TIM DLY MS= 3.133  
 ANGLE OF ARRIVAL SKYWAVE= 29.8 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .62  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 298.3

Figure 5. Output of air/ground model for circuit (2) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTR	45.0	5.0	1.0	84.7	1177.7
RECEIVER	45.0	20.0	1.0	275.3	1177.7

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.500	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	588.874	294.437	883.311	588.874	588.874	
LATITUDE	45.246	45.184	45.184	45.246	45.246	
LONGITUDE	-12.500	-8.742	-16.258	-12.500	-12.500	
GEOM. LAT.	45.777	46.467	44.971	45.777	45.777	
TIME HOURS	11.833	0.000	0.000	0.000	0.000	
ABSORP FAC	.804	0.000	0.000	0.000	0.000	
E LAYER CR	2.989	0.000	0.000	0.000	0.000	
F LAYER BT	221.780	0.000	0.000	0.000	0.000	
HT OF FMAX	276.680	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.294	0.000	0.000	0.000	0.000	
F LAYER CT	10.196	0.000	0.000	0.000	0.000	
ES UP DEC	3.753	0.000	0.000	0.000	0.000	
ES MED VAL	3.252	0.000	0.000	0.000	0.000	
ES LOW DEC	2.653	0.000	0.000	0.000	0.000	
EX SYS STS	9.009	7.160	4.104	3.019	2.019	1.019
AND STATIS	-174.583	8.056	6.534	3.462	2.254	5.598

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	
TK OFF ANG	7.600	0.000	19.457	39.398	54.728	0.000	0.000	
VIRTUAL HT	107.434	0.000	231.899	255.839	291.751	0.000	0.000	
TM DLY MS.	4.024	0.000	4.312	5.286	7.114	0.000	0.000	
SKY WV LOS	114.908	1000.000	115.508	117.277	119.856	1000.000	1000.000	
ABSRP LOSS	9.189	1000.000	5.394	6.180	7.312	1000.000	1000.000	
GND REF LS	0.000	1000.000	0.000	8.164	9.438	1000.000	1000.000	
TRNSMSN LS	133.107	1000.000	129.911	140.630	145.615	1000.000	1000.000	
FIELD STPN	21.911	-1000.000	25.107	14.388	9.402	-1000.000	-1000.000	
SIG POWER	-106.117	-1000.000	-102.921	-113.640	-118.626	-1000.000	-1000.000	
S/N IN DB.	57.142	-1000.000	60.338	49.619	44.634	-1000.000	-1000.000	
FRACT DAYS	.994	0.000	.994	.885	.592	0.000	0.000	
FRACT S/N	.594	0.000	.718	.258	.091	0.000	0.000	
RELIABILITY	.591	0.000	.714	.228	.054	0.000	0.000	
SERV. PROB	.021	0.000	.086	.000	0.000	0.000	0.000	

MODE= 1 E MULTI PTH PROB= .01 PATH LOSS=123.9 UD=120.0 LD=127.9 TIM DLY MS= 4.024  
 ANGLE OF ARRIVAL SKYWAVE= 7.6 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .59  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 375.6

Figure 6. Output of air/ground model for circuit (3) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/92 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	45.0	5.0	1.0	82.9	1568.6
RECEIVER	45.0	25.0	1.0	277.1	1568.6

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGDWB	MP-TMDLY
11.0	.500	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	784.285	392.142	1176.427	784.285	784.285	
LATITUDE	45.439	45.328	45.328	45.439	45.439	
LONGITUDE	-15.000	-9.981	-20.019	-15.000	-15.000	
GEOM. LAT.	45.465	46.358	44.369	45.465	45.465	
TIME HOURS	12.000	0.000	0.000	0.000	0.000	
ABSORP FAC	.803	0.000	0.000	0.000	0.000	
E LAYER CR	2.981	0.000	0.000	0.000	0.000	
F LAYER BT	221.990	0.000	0.000	0.000	0.000	
HT OF FMAX	278.360	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.301	0.000	0.000	0.000	0.000	
F LAYER CT	10.244	0.000	0.000	0.000	0.000	
ES UP DEC	3.751	0.000	0.000	0.000	0.000	
ES MED VAL	3.259	0.000	0.000	0.000	0.000	
ES LOW DEC	2.650	0.000	0.000	0.000	0.000	
EX SYS STS	9.014	7.740	4.084	3.014	2.014	1.014
AND STATIS	-174.450	8.067	6.542	3.497	2.231	5.616

	E MODES			F MODES			EF MODES
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000
TK OFF ANG	3.747	0.000	13.864	29.984	43.853	0.000	0.000
VIRTUAL HT	101.019	0.000	230.382	242.761	264.897	0.000	0.000
TM DLY MS.	5.313	0.000	5.570	6.267	7.555	0.000	0.000
SKY WV LOS	117.321	1000.000	117.731	118.755	120.379	1000.000	1000.000
ABSRP LOSS	10.743	1000.000	6.822	7.675	8.538	1000.000	1000.000
GND REF LS	0.000	1000.000	0.000	7.401	16.760	1000.000	1000.000
TRNSMSN LS	137.078	1000.000	133.567	142.845	154.692	1000.000	1000.000
FIELD STRN	17.940	-1000.000	21.451	12.172	.326	-1000.000	-1000.000
SIG POWER	-110.088	-1000.000	-106.577	-115.855	-127.702	-1000.000	-1000.000
S/N IN DB.	53.161	-1000.000	56.672	47.394	35.547	-1000.000	-1000.000
FRACT DAYS	.994	0.000	.994	.798	0.000	0.000	0.000
FRACT S/N	.417	0.000	.572	.174	.001	0.000	0.000
RELIABILITY	.415	0.000	.569	.173	.001	0.000	0.000
SERV. PROB	.001	0.000	.012	.000	0.000	0.000	0.000

MODE= 1 E MULTI PTH PROB= .01 PATH LOSS=127.2 UD=123.2 LD=131.1 TIM DLY MS= 5.313  
 ANGLE OF ARRIVAL SKYWAVE= 3.7 NOISE LEVEL= -163.2 CIRCUIT RELIABILITY= .42  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 451.8

Figure 7. Output of air/ground model for circuit (4) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	45.0	5.0	1.0	81.1	1957.9
RECEIVER	45.0	30.0	1.0	278.9	1957.9

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGDOW	MP-TMDLY
11.0	.500	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	978.933	489.467	1468.400	978.933	978.933	
LATITUDE	45.687	45.514	45.514	45.687	45.687	
LONGITUDE	-17.500	-11.212	-23.788	-17.500	-17.500	
GEDM. LAT.	45.208	46.291	43.813	45.208	45.208	
TIME HOURS	12.167	0.000	0.000	0.000	0.000	
ABSORP FAC	.798	0.000	0.000	0.000	0.000	
E LAYER CR	2.963	0.000	0.000	0.000	0.000	
F LAYER BT	222.165	0.000	0.000	0.000	0.000	
HT OF FMAX	279.641	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.310	0.000	0.000	0.000	0.000	
F LAYER CT	10.280	0.000	0.000	0.000	0.000	
ES UP DEC	3.738	0.000	0.000	0.000	0.000	
ES MED VAL	3.253	0.000	0.000	0.000	0.000	
ES LOW DEC	2.639	0.000	0.000	0.000	0.000	
EX SYS STS	9.008	7.678	4.047	3.008	2.008	1.008
AND STATIS	-174.322	8.078	6.550	3.532	2.208	5.633

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	
TK OFF ANG	1.355	0.000	11.742	23.839	35.962	0.000	0.000	
VIRTUAL HT	99.654	0.000	0.000	236.458	251.552	0.000	0.000	
TM DLY MS.	6.609	0.000	0.000	7.398	8.383	0.000	0.000	
SKY WV LOS	119.217	1000.000	1000.000	120.196	121.283	1000.000	1000.000	
ABSRP LOSS	11.282	1000.000	1000.000	9.169	9.898	1000.000	1000.000	
GND REF LS	0.000	1000.000	1000.000	6.598	15.880	1000.000	1000.000	
TRNSMSN LS	139.506	1000.000	1000.000	144.971	156.068	1000.000	1000.000	
FIELD STRN	15.511	-1000.000	-1000.000	10.047	-1.050	-1000.000	-1000.000	
SIG POWER	-112.517	-1000.000	-1000.000	-117.981	-129.078	-1000.000	-1000.000	
S/N IN DB.	50.723	-1000.000	-1000.000	45.258	34.161	-1000.000	-1000.000	
FRACT DAYS	.994	0.000	0.000	.994	.980	0.000	0.000	
FRACT S/N	.307	0.000	0.000	.106	.000	0.000	0.000	
RELIABILTY	.305	0.000	0.000	.106	.000	0.000	0.000	
SERV. PROB	.000	0.000	0.000	0.000	0.000	0.000	0.000	

MODE= 1 E MULTI PTH PROB= .01 PATH LOSS=129.7 UD=125.7 LD=133.6 TIM DLY MS= 6.609  
 ANGLE OF ARRIVAL SKYWAVE= 1.4 NOISE LEVEL= -163.2 CIRCUIT RELIABILITY= .31  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 527.0

Figure 8. Output of air/ground model for circuit (5) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	55.0	15.0	1.0	180.0	556.0
RECEIVER	50.0	15.0	1.0	.0	556.0

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	277.996	138.998	416.994	277.996	277.996	
LATITUDE	52.500	53.750	51.250	52.500	52.500	
LONGITUDE	-15.002	-15.002	-15.003	-15.002	-15.002	
GEOM. LAT.	52.196	53.377	51.011	52.196	52.196	
TIME HOURS	12.000	0.000	0.000	0.000	0.000	
ABSORP FAC	.678	0.000	0.000	0.000	0.000	
E LAYER CR	2.616	0.000	0.000	0.000	0.000	
F LAYER BT	222.412	0.000	0.000	0.000	0.000	
HT OF FMAX	274.255	0.000	0.000	0.000	0.000	
GYRD FREQ.	1.352	0.000	0.000	0.000	0.000	
F LAYER CT	10.189	0.000	0.000	0.000	0.000	
ES UP DEC	3.644	0.000	0.000	0.000	0.000	
ES MED VAL	2.959	0.000	0.000	0.000	0.000	
ES LOW DEC	2.367	0.000	0.000	0.000	0.000	
EX SYS STS	9.000	7.500	4.000	3.000	2.000	1.000
AND STATIS	-174.719	8.045	6.526	3.427	2.278	5.581

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	
TK OFF ANG	0.000	0.000	41.253	67.853	75.893	0.000	0.000	
VIRTUAL HT	0.000	0.000	258.068	361.486	391.111	0.000	0.000	
TM DLY MS.	0.000	0.000	2.566	5.198	8.076	0.000	0.000	
SKY WV LOS	1000.000	1000.000	110.999	117.131	120.958	1000.000	1000.000	
ABSRP LOSS	1000.000	1000.000	2.607	3.775	5.417	1000.000	1000.000	
GND REF LS	1000.000	1000.000	0.000	8.774	17.577	1000.000	1000.000	
TRNSMSN LS	1000.000	1000.000	122.606	138.681	152.952	1000.000	1000.000	
FIELD STRN	-1000.000	-1000.000	25.422	9.347	-4.924	-1000.000	-1000.000	
SIG POWER	-1000.000	-1000.000	-102.606	-118.681	-132.952	-1000.000	-1000.000	
S/N IN DB.	-1000.000	-1000.000	60.663	44.589	30.318	-1000.000	-1000.000	
FRACT DAYS	0.000	0.000	.854	.499	.497	0.000	0.000	
FRACT S/N	0.000	0.000	.725	.088	.000	0.000	0.000	
RELIABILTY	0.000	0.000	.619	.044	.000	0.000	0.000	
SERV. PROR	0.000	0.000	.070	0.000	0.000	0.000	0.000	

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=112.9 UD=108.9 LD=116.8 TIM DLY MS= 2.566  
 ANGLE OF ARRIVAL SKYWAVE= 41.3 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .72  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 252.0

Figure 9. Output of air/ground model for circuit (6) in Table 3, 11 MHz.



TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTR	55.0	15.0	1.0	180.0	1112.0
RECEIVER	45.0	15.0	1.0	.0	1112.0

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	555.992	277.996	833.988	555.992	555.992	
LATITUDE	50.000	52.500	47.500	50.000	50.000	
LONGITUDE	-15.003	-15.002	-15.004	-15.003	-15.003	
GEOM. LAT.	49.823	52.196	47.438	49.823	49.823	
TIME HOURS	12.000	0.000	0.000	0.000	0.000	
ABSORP FAC	.730	0.000	0.000	0.000	0.000	
E LAYER CR	2.750	0.000	0.000	0.000	0.000	
F LAYER BT	221.954	0.000	0.000	0.000	0.000	
HT OF FMAX	274.857	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.336	0.000	0.000	0.000	0.000	
F LAYER CT	10.286	0.000	0.000	0.000	0.000	
ES UP DEC	3.627	0.000	0.000	0.000	0.000	
ES MED VAL	3.076	0.000	0.000	0.000	0.000	
ES LOW DEC	2.480	0.000	0.000	0.000	0.000	
EX SYS STS	9.000	7.600	4.000	3.000	2.000	1.000
AND STATIS	-174.715	8.045	6.526	3.427	2.278	5.581

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	0.000	0.000	20.516	41.178	56.286	0.000	0.000	0.000
VIRTUAL HT	0.000	0.000	232.449	257.145	291.973	0.000	0.000	0.000
TM DLY MS.	0.000	0.000	4.100	5.125	6.988	0.000	0.000	0.000
SKY WV LOS	1000.000	1000.000	115.069	117.009	119.701	1000.000	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	4.816	5.551	6.676	1000.000	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	8.259	17.379	1000.000	1000.000	1000.000
TRNSMSN LS	1000.000	1000.000	128.885	139.819	152.756	1000.000	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	19.142	8.209	-4.728	-1000.000	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-108.885	-119.819	-132.756	-1000.000	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	54.383	43.450	30.513	-1000.000	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.994	.870	.590	0.000	0.000	0.000
FRACT S/N	0.000	0.000	.472	.063	.000	0.000	0.000	0.000
RELIABILITY	0.000	0.000	.469	.055	.000	0.000	0.000	0.000
SERV. PROB	0.000	0.000	.003	0.000	0.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=119.1 UD=115.2 LD=123.1 TIM DLY MS= 4.100  
 ANGLE OF ARRIVAL SKYWAVE= 20.5 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .47  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 362.8

Figure 10. Output of air/ground model for circuit (7) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG.	DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	55.0	15.0		1.0	190.0	1668.0
RECEIVER	40.0	15.0		1.0	.0	1668.0

FREQ-MHZ	PWP-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	833.938	416.994	1250.982	833.988	833.988	
LATITUDE	47.500	51.250	43.750	47.500	47.500	
LONGITUDE	-15.004	-15.003	-15.004	-15.004	-15.004	
GEOM. LAT.	47.438	51.011	43.842	47.438	47.438	
TIME HOURS	12.000	0.000	0.000	0.000	0.000	
ABSORP FAC	.771	0.000	0.000	0.000	0.000	
E LAYER CR	2.878	0.000	0.000	0.000	0.000	
F LAYER BT	221.927	0.000	0.000	0.000	0.000	
HT OF FMAX	276.616	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.317	0.000	0.000	0.000	0.000	
F LAYER CT	10.269	0.000	0.000	0.000	0.000	
ES UP DEC	3.584	0.000	0.000	0.000	0.000	
ES MED VAL	3.178	0.000	0.000	0.000	0.000	
ES LOW DEC	2.575	0.000	0.000	0.000	0.000	
EX SYS STS	9.000	7.500	4.000	3.000	2.000	1.000
AND STATIS	-174.588	8.045	6.526	3.427	2.278	5.581

	F MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	3.125	0.000	12.683	28.049	41.370	0.000	0.000	0.000
VIRTUAL HT	101.505	0.000	229.461	239.813	258.724	0.000	0.000	0.000
TM DLY MS.	5.645	0.000	5.891	6.537	7.712	0.000	0.000	0.000
SKY WV LOS	117.847	1000.000	118.219	119.122	120.558	1000.000	1000.000	1000.000
ABSRP LOSS	10.620	1000.000	6.992	7.860	8.660	1000.000	1000.000	1000.000
GND REF LS	0.000	1000.000	0.000	7.178	12.589	1000.000	1000.000	1000.000
TRNSMSN LS	137.467	1000.000	134.211	143.160	150.807	1000.000	1000.000	1000.000
FIELD STRN	10.561	-1000.000	13.817	4.868	-2.779	-1000.000	-1000.000	-1000.000
SIG POWER	-117.467	-1000.000	-114.211	-123.160	-130.807	-1000.000	-1000.000	-1000.000
S/N IN DB.	45.800	-1000.000	49.056	40.107	32.460	-1000.000	-1000.000	-1000.000
FRACT DAYS	.994	0.000	.994	.994	.858	0.000	0.000	0.000
FRACT S/N	.121	0.000	.236	.018	.000	0.000	0.000	0.000
RELIABILTY	.120	0.000	.234	.018	.000	0.000	0.000	0.000
SERV. PROR	0.000	0.000	.000	0.000	0.000	0.000	0.000	0.000

MODE= 1 E MULTI PTH PROB= .01 PATH LOSS=127.7 UD=123.8 LD=131.7 TIM DLY MS= 5.645  
 ANGLE OF ARRIVAL SKYWAVE= 3.1 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .12  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 471.0

Figure 11. Output of air/ground model for circuit (8) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	55.0	15.0	1.0	180.0	2224.0
RECEIVER	35.0	15.0	1.0	.0	2224.0

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.500	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	1111.984	555.992	1667.976	1111.984	1111.984	
LATITUDE	45.000	50.000	40.000	45.000	45.000	
LONGITUDE	-15.004	-15.003	-15.005	-15.004	-15.004	
GEOM. LAT.	45.043	49.823	40.228	45.043	45.043	
TIME HOURS	12.000	12.000	12.000	0.000	0.000	
ARSDRP FAC	.808	.730	.858	0.000	0.000	
F LAYER CR	3.002	2.750	3.228	0.000	0.000	
F LAYER BT	222.052	221.954	222.980	0.000	0.000	
HT OF FMAX	278.899	274.857	286.265	0.000	0.000	
GYRD FREQ.	1.297	1.336	1.249	0.000	0.000	
F LAYER CT	10.233	10.286	10.168	0.000	0.000	
ES UP DEC	3.777	3.627	4.156	0.000	0.000	
ES MED VAL	3.275	3.076	3.470	0.000	0.000	
ES LOW DEC	2.664	2.480	2.824	0.000	0.000	
EX SYS STS	9.350	9.100	4.900	3.550	2.200	1.200
AND STATIS	-174.672	8.045	6.526	3.427	2.278	5.581

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	E MODES			F MODES			EF MODES
NO OF HOPS	1.000	2.000	2.000	3.000	4.000	0.000	0.000
TK OFF ANG	.160	0.000	20.611	31.710	41.628	0.000	0.000
VIRTUAL HT	101.474	0.000	233.658	245.570	261.390	0.000	0.000
TM DLY MS.	7.498	0.000	8.206	9.051	10.328	0.000	0.000
SKY WV LOS	120.314	1000.000	121.097	121.948	123.095	1000.000	1000.000
ABSRP LOSS	11.298	1000.000	10.191	10.866	11.690	1000.000	1000.000
GND REF LS	0.000	1000.000	4.025	7.817	12.783	1000.000	1000.000
TRNSMSN LS	140.961	1000.000	144.664	149.981	156.918	1000.000	1000.000
FIELD STRN	14.056	-1000.000	10.354	5.037	-1.900	-1000.000	-1000.000
SIG POWER	-113.972	-1000.000	-117.674	-122.991	-129.928	-1000.000	-1000.000
S/N IN DB.	49.294	-1000.000	45.592	40.275	33.338	-1000.000	-1000.000
FRACT DAYS	.994	0.000	.994	.994	.850	0.000	0.000
FRACT S/N	.263	0.000	.133	.026	.000	0.000	0.000
RELIABILTY	.261	0.000	.132	.026	.000	0.000	0.000
SERV. PROB	.000	0.000	0.000	0.000	0.000	0.000	0.000

MODE= 1 E MULTI PTH PROB= .01 PATH LOSS=129.3 UD=124.8 LD=133.8 TIM DLY MS= 7.498  
 ANGLE OF ARRIVAL SKYWAVE= .2 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .25  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 578.2

Figure 12. Output of air/ground model for circuit (9) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= RR.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	55.0	15.0	1.0	180.0	2780.0
RECEIVER	30.0	15.0	1.0	.0	2780.0

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGDOW	MP-TMDLY
11.0	.500	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	1389.980	694.990	2084.970	1389.980	1389.980	
LATITUDE	42.500	48.750	36.250	42.500	42.500	
LONGITUDE	-15.005	-15.003	-15.005	-15.005	-15.005	
GEOM. LAT.	42.639	48.632	36.600	42.639	42.539	
TIME HOURS	12.000	12.000	12.000	0.000	0.000	
ABSORP FAC	.838	.751	.876	0.000	0.000	
E LAYER CR	3.120	2.814	3.376	0.000	0.000	
F LAYER BT	222.405	221.940	223.966	0.000	0.000	
HT OF FMAX	281.979	275.735	294.477	0.000	0.000	
GYRO FREQ.	1.275	1.327	1.207	0.000	0.000	
F LAYER CT	10.170	10.278	10.359	0.000	0.000	
ES UP DEC	3.925	3.655	4.606	0.000	0.000	
ES MED VAL	3.366	3.127	3.676	0.000	0.000	
ES LOW DEC	2.744	2.527	2.961	0.000	0.000	
EX SYS STS	9.600	9.600	5.200	4.000	2.300	1.300
AND STATIS	-174.561	8.045	6.526	3.427	2.278	5.581

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	E MODES			F MODES			EF MODES	
NO OF HOPS	2.000	3.000	2.000	3.000	4.000	0.000	0.000	
TK OFF ANG	5.432	0.000	16.075	25.339	34.073	0.000	0.000	
VIRTUAL HT	105.551	0.000	231.352	239.422	250.947	0.000	0.000	
TM DLY MS.	9.450	0.000	9.981	10.636	11.630	0.000	0.000	
SKY WV LOS	122.323	1000.000	122.798	123.350	124.126	1000.000	1000.000	
ABSRP LOSS	20.275	1000.000	12.413	13.222	13.900	1000.000	1000.000	
GND REF LS	1.037	1000.000	.424	7.021	8.225	1000.000	1000.000	
TRNSMSN LS	153.235	1000.000	145.235	153.193	155.851	1000.000	1000.000	
FIELD STRN	1.782	-1000.000	9.783	1.824	-.833	-1000.000	-1000.000	
SIG POWER	-126.246	-1000.000	-118.245	-126.204	-128.861	-1000.000	-1000.000	
S/N IN DB.	37.182	-1000.000	45.182	37.224	34.566	-1000.000	-1000.000	
FRACT DAYS	.994	0.000	.994	.994	.994	0.000	0.000	
FRACT S/N	.007	0.000	.130	.007	.001	0.000	0.000	
RELIABILITY	.007	0.000	.129	.007	.001	0.000	0.000	
SERV. PROB	0.000	0.000	0.000	0.000	0.000	0.000	0.000	

MODE= 2 E MULTI PTH PROB= .01 PATH LOSS=140.9 UD=136.0 LD=145.9 TIM DLY MS= 9.450  
 ANGLE OF ARRIVAL SKYWAVE= 5.4 NOISE LEVEL= -163.4 CIRCUIT RELIABILITY= .01  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 684.9

Figure 13. Output of air/ground model for circuit (10) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	45.0	10.0	1.0	89.6	78.6
RECEIVER	45.0	11.0	1.0	270.4	78.6

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	39.314	19.657	58.971	39.314	39.314	
LATITUDE	45.001	45.001	45.001	45.001	45.001	
LONGITUDE	-10.500	-10.250	-10.750	-10.500	-10.500	
GEOM. LAT.	45.940	45.990	45.890	45.940	45.940	
TIME HOURS	11.700	0.000	0.000	0.000	0.000	
ABSORP FAC	.805	0.000	0.000	0.000	0.000	
E LAYER CR	3.000	0.000	0.000	0.000	0.000	
F LAYER BT	221.597	0.000	0.000	0.000	0.000	
HT OF FMAX	275.409	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.288	0.000	0.000	0.000	0.000	
F LAYER CT	10.158	0.000	0.000	0.000	0.000	
ES UP DEC	3.758	0.000	0.000	0.000	0.000	
ES MED VAL	3.250	0.000	0.000	0.000	0.000	
ES LOW DEC	2.659	0.000	0.000	0.000	0.000	
EX SYS STS	9.002	6.702	4.127	3.025	2.025	1.025
AND STATIS	-174.821	8.036	6.520	3.399	2.296	5.567

	E MODES			F MODES			EF MODES
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000
TK OFF ANG	0.000	0.000	84.875	87.704	88.478	0.000	0.000
VIRTUAL HT	0.000	0.000	469.508	529.783	533.118	0.000	0.000
TM DLY MS.	0.000	0.000	3.152	7.091	10.699	0.000	0.000
SKY WV LOS	1000.000	1000.000	112.787	119.829	123.401	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	2.016	4.019	6.025	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	.588	1.177	1000.000	1000.000
TRNSMSN LS	1000.000	1000.000	123.805	133.438	139.606	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	24.222	14.590	8.421	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-103.805	-113.438	-119.606	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	59.471	49.838	43.670	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.495	.494	.494	0.000	0.000
FRACT S/N	0.000	0.000	.691	.266	.071	0.000	0.000
RELIABILTY	0.000	0.000	.342	.131	.035	0.000	0.000
SERV. PROR	0.000	0.000	.036	.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROR= .01 PATH LOSS=115.2 UD=111.2 LD=119.2 TIM DLY MS= 3.152  
 ANGLE OF ARRIVAL SKYWAVE= 84.9 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .69  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 147.9

Figure 14. Output of air/ground model for circuit (11) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	45.0	10.0	1.0	89.3	157.3
RECEIVER	45.0	12.0	1.0	270.7	157.3

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	78.627	39.314	117.941	78.627	78.627	
LATITUDE	45.004	45.003	45.003	45.004	45.004	
LONGITUDE	-11.000	-10.500	-11.500	-11.000	-11.000	
GEOM. LAT.	45.844	45.942	45.743	45.844	45.844	
TIME HOURS	11.733	0.000	0.000	0.000	0.000	
ABSORP FAC	.805	0.000	0.000	0.000	0.000	
E LAYER CR	3.000	0.000	0.000	0.000	0.000	
F LAYER BT	221.648	0.000	0.000	0.000	0.000	
HT OF FMAX	275.790	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.289	0.000	0.000	0.000	0.000	
F LAYER CT	10.166	0.000	0.000	0.000	0.000	
ES UP DEC	3.760	0.000	0.000	0.000	0.000	
ES MED VAL	3.252	0.000	0.000	0.000	0.000	
ES LOW DEC	2.659	0.000	0.000	0.000	0.000	
EX SYS STS	9.005	6.829	4.129	3.025	2.025	1.025
AND STATIS	-174.795	8.038	5.521	3.406	2.292	5.571

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	0.000	0.000	78.532	84.891	86.635	0.000	0.000	0.000
VIRTUAL HT	0.000	0.000	411.866	471.112	478.009	0.000	0.000	0.000
TM DLY MS.	0.000	0.000	2.809	6.326	9.608	0.000	0.000	0.000
SKY WV LOS	1000.000	1000.000	111.785	118.837	122.467	1000.000	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	2.048	4.032	6.035	1000.000	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	.626	1.255	1000.000	1000.000	1000.000
TRNSMSN LS	1000.000	1000.000	122.838	132.501	138.762	1000.000	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	25.190	15.527	9.266	-1000.000	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-102.838	-112.501	-118.762	-1000.000	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	60.437	50.774	44.513	-1000.000	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.496	.495	.495	0.000	0.000	0.000
FRACT S/N	0.000	0.000	.725	.307	.090	0.000	0.000	0.000
RELIABILITY	0.000	0.000	.359	.152	.044	0.000	0.000	0.000
SERV. PROB	0.000	0.000	.050	.000	0.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=114.1 UD=110.1 LD=118.1 TIM DLY MS= 2.809  
 ANGLE OF ARRIVAL SKYWAVE= 78.5 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .72  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 165.9

Figure 15. Output of air/ground model for circuit (12) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG.	DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	45.0	10.0		1.0	88.9	235.9
RECEIVER	45.0	13.0		1.0	271.1	235.9

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	117.937	58.968	176.905	117.937	117.937	
LATITUDE	45.010	45.007	45.007	45.010	45.010	
LONGITUDE	-11.500	-10.750	-12.250	-11.500	-11.500	
GEOM. LAT.	45.749	45.896	45.598	45.749	45.749	
TIME HOURS	11.767	0.000	0.000	0.000	0.000	
ABSORP FAC	.806	0.000	0.000	0.000	0.000	
E LAYER CR	3.000	0.000	0.000	0.000	0.000	
F LAYER BT	221.698	0.000	0.000	0.000	0.000	
HT OF FMAX	276.170	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.290	0.000	0.000	0.000	0.000	
F LAYER CT	10.175	0.000	0.000	0.000	0.000	
ES UP DEC	3.762	0.000	0.000	0.000	0.000	
ES MED VAL	3.255	0.000	0.000	0.000	0.000	
ES LOW DEC	2.660	0.000	0.000	0.000	0.000	
EX SYS STS	9.007	6.956	4.131	3.025	2.025	1.025
AND STATIS	-174.768	8.041	6.523	3.413	2.287	5.574

	E MODES			F MODES			EF MODES	
NO OF HDPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	0.000	0.000	71.853	81.543	84.907	0.000	0.000	0.000
VIRTUAL HT	0.000	0.000	381.203	421.879	472.708	0.000	0.000	0.000
TM DLY MS.	0.000	0.000	2.677	5.704	9.521	0.000	0.000	0.000
SKY WV LOS	1000.000	1000.000	111.368	117.938	122.388	1000.000	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	2.110	4.060	6.050	1000.000	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	.675	1.359	1000.000	1000.000	1000.000
TRNSMSN LS	1000.000	1000.000	122.486	131.681	138.804	1000.000	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	25.542	16.347	9.224	-1000.000	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-102.486	-111.681	-118.804	-1000.000	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	60.787	51.592	44.469	-1000.000	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.497	.495	.495	0.000	0.000	0.000
FRACT S/N	0.000	0.000	.735	.344	.089	0.000	0.000	0.000
RELIABILTY	0.000	0.000	.366	.170	.044	0.000	0.000	0.000
SERV. PROB	0.000	0.000	.054	.000	0.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=113.6 UD=109.6 LD=117.6 TIM DLY MS= 2.677  
 ANGLE OF ARRIVAL SKYWAVE= 71.9 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .74  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 184.3

Figure 16. Output of air/ground model for circuit (13) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTR	45.0	10.0	1.0	88.6	314.5
RECEIVER	45.0	14.0	1.0	271.4	314.5

FREQ-MHZ	PWR-KW	REQ	S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55		SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	157.242	78.621	235.864	157.242	157.242	
LATITUDE	45.017	45.013	45.013	45.017	45.017	
LONGITUDE	-12.000	-11.000	-13.000	-12.000	-12.000	
GEOM. LAT.	45.657	45.852	45.454	45.657	45.657	
TIME HOURS	11.800	0.000	0.000	0.000	0.000	
ABSORP FAC	.806	0.000	0.000	0.000	0.000	
E LAYER CR	3.000	0.000	0.000	0.000	0.000	
F LAYER BT	221.748	0.000	0.000	0.000	0.000	
HT OF FMAX	276.547	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.291	0.000	0.000	0.000	0.000	
F LAYER CT	10.183	0.000	0.000	0.000	0.000	
ES UP DEC	3.763	0.000	0.000	0.000	0.000	
ES MED VAL	3.257	0.000	0.000	0.000	0.000	
ES LOW DEC	2.660	0.000	0.000	0.000	0.000	
EX SYS STS	9.010	7.081	4.133	3.025	2.025	1.025
AND STATIS	-174.742	8.043	6.524	3.420	2.282	5.578

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	0.000	0.000	64.354	78.596	83.216	0.000	0.000	0.000
VIRTUAL HT	0.000	0.000	345.986	414.346	472.203	0.000	0.000	0.000
TM DLY MS.	0.000	0.000	2.555	5.650	9.538	0.000	0.000	0.000
SKY WV LOS	1000.000	1000.000	110.962	117.855	122.404	1000.000	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	2.221	4.097	6.069	1000.000	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	.741	1.507	1000.000	1000.000	1000.000
TRNSMSN LS	1000.000	1000.000	122.193	131.703	138.989	1000.000	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	25.835	16.325	9.039	-1000.000	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-102.193	-111.703	-118.989	-1000.000	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	61.078	51.568	44.282	-1000.000	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.500	.496	.495	0.000	0.000	0.000
FRACT S/N	0.000	0.000	.744	.343	.084	0.000	0.000	0.000
RELIABILITY	0.000	0.000	.372	.170	.042	0.000	0.000	0.000
SERV. PROB	0.000	0.000	.058	.000	0.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=113.1 UD=109.1 LD=117.1 TIM DLY MS= 2.555  
 ANGLE OF ARRIVAL SKYWAVE= 64.4 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .74  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 201.6

Figure 17. Output of air/ground model for circuit (14) in Table 3, 11 MHz.



TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG.	DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	45.0	10.0		1.0	88.2	393.1
RECEIVER	45.0	15.0		1.0	271.8	393.1

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.100	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	196.542	98.271	294.813	196.542	196.542	
LATITUDE	45.027	45.020	45.020	45.027	45.027	
LONGITUDE	-12.500	-11.250	-13.750	-12.500	-12.500	
GEOM. LAT.	45.567	45.809	45.312	45.567	45.567	
TIME HOURS	11.833	0.000	0.000	0.000	0.000	
ABSORP FAC	.806	0.000	0.000	0.000	0.000	
E LAYER CR	3.000	0.000	0.000	0.000	0.000	
F LAYER RT	221.797	0.000	0.000	0.000	0.000	
HT OF FMAX	276.922	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.292	0.000	0.000	0.000	0.000	
F LAYER CT	10.192	0.000	0.000	0.000	0.000	
ES UP DEC	3.765	0.000	0.000	0.000	0.000	
ES MED VAL	3.260	0.000	0.000	0.000	0.000	
ES LOW DEC	2.660	0.000	0.000	0.000	0.000	
EX SYS STS	9.012	7.207	4.134	3.024	2.024	1.024
AND STATIS	-174.715	8.045	6.526	3.427	2.278	5.581

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	
TK OFF ANG	0.000	0.000	54.732	75.353	80.586	0.000	0.000	
VIRTUAL HT	0.000	0.000	292.180	399.060	420.293	0.000	0.000	
TM DLY MS.	0.000	0.000	2.375	5.510	8.545	0.000	0.000	
SKY WV LOS	1000.000	1000.000	110.326	117.637	121.448	1000.000	1000.000	
ABSRP LOSS	1000.000	1000.000	2.443	4.150	6.109	1000.000	1000.000	
GND REF LS	1000.000	1000.000	0.000	.836	1.751	1000.000	1000.000	
TRNSMSN LS	1000.000	1000.000	121.781	131.635	138.320	1000.000	1000.000	
FIELD STRN	-1000.000	-1000.000	26.247	16.393	9.708	-1000.000	-1000.000	
SIG POWER	-1000.000	-1000.000	-101.781	-111.635	-118.320	-1000.000	-1000.000	
S/N IN DB.	-1000.000	-1000.000	61.488	51.634	44.949	-1000.000	-1000.000	
FRACT DAYS	0.000	0.000	.592	.497	.496	0.000	0.000	
FRACT S/N	0.000	0.000	.756	.346	.100	0.000	0.000	
RELIABILITY	0.000	0.000	.448	.172	.049	0.000	0.000	
SERV. PROB	0.000	0.000	.075	.000	0.000	0.000	0.000	

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=112.5 UD=108.6 LD=116.5 TIM DLY MS= 2.375  
 ANGLE OF ARRIVAL SKYWAVE= 54.7 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .76  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 218.3

Figure 18. Output of air/ground model for circuit (15) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTR	45.0	10.0	1.0	87.9	471.7
RECEIVER	45.0	16.0	1.0	272.1	471.7

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.200	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	235.834	117.917	353.750	235.834	235.834	
LATITUDE	45.039	45.029	45.029	45.039	45.039	
LONGITUDE	-13.000	-11.499	-14.501	-13.000	-13.000	
GEOM. LAT.	45.479	45.768	45.171	45.479	45.479	
TIMF HOURS	11.867	0.000	0.000	0.000	0.000	
ABSORP FAC	.806	0.000	0.000	0.000	0.000	
E LAYER CR	2.999	0.000	0.000	0.000	0.000	
F LAYER BT	221.846	0.000	0.000	0.000	0.000	
HT OF FMAX	277.296	0.000	0.000	0.000	0.000	
GYRD FREQ.	1.294	0.000	0.000	0.000	0.000	
F LAYER CT	10.200	0.000	0.000	0.000	0.000	
ES UP DEC	3.766	0.000	0.000	0.000	0.000	
ES MED VAL	3.252	0.000	0.000	0.000	0.000	
ES LOW DEC	2.661	0.000	0.000	0.000	0.000	
EX SYS STS	9.014	7.331	4.134	3.024	2.024	1.024
AND STATIS	-174.689	8.047	6.527	3.434	2.273	5.585

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	
TK OFF ANG	0.000	0.000	47.713	71.986	78.658	0.000	0.000	
VIRTUAL HT	0.000	0.000	272.927	384.333	416.803	0.000	0.000	
TM DLY MS.	0.000	0.000	2.438	5.394	8.523	0.000	0.000	
SKY WV LOS	1000.000	1000.000	110.555	117.452	121.426	1000.000	1000.000	
ABSRP LOSS	1000.000	1000.000	2.683	4.220	6.146	1000.000	1000.000	
GND REF LS	1000.000	1000.000	0.000	.989	2.315	1000.000	1000.000	
TRNSMSN LS	1000.000	1000.000	122.252	131.676	138.902	1000.000	1000.000	
FIELD STRN	-1000.000	-1000.000	28.786	19.362	12.136	-1000.000	-1000.000	
SIG POWER	-1000.000	-1000.000	-99.242	-108.666	-115.892	-1000.000	-1000.000	
S/N IN DB.	-1000.000	-1000.000	64.025	54.601	47.375	-1000.000	-1000.000	
FRACT DAYS	0.000	0.000	.707	.498	.496	0.000	0.000	
FRACT S/N	0.000	0.000	.825	.482	.173	0.000	0.000	
RELIABILTY	0.000	0.000	.583	.240	.086	0.000	0.000	
SERV. PROB	0.000	0.000	.176	.002	.000	0.000	0.000	

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=112.9 UD=108.9 LD=116.8 TIM DLY MS= 2.438  
 ANGLE OF ARRIVAL SKYWAVE= 47.7 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .83  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 234.7

Figure 19. Output of air/ground model for circuit (16) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG.	DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	45.0	10.0		1.0	87.2	628.8
RECEIVER	45.0	18.0		1.0	272.8	628.8

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.200	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	314.389	157.194	471.583	314.389	314.389	
LATITUDE	45.070	45.052	45.052	45.070	45.070	
LONGITUDE	-14.000	-11.999	-16.001	-14.000	-14.000	
GEOM. LAT.	45.309	45.691	44.896	45.309	45.309	
TIME HOURS	11.933	0.000	0.000	0.000	0.000	
ABSORP FAC	.807	0.000	0.000	0.000	0.000	
E LAYER CR	2.998	0.000	0.000	0.000	0.000	
F LAYER HT	221.942	0.000	0.000	0.000	0.000	
HT OF FMAX	278.034	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.296	0.000	0.000	0.000	0.000	
F LAYER CT	10.218	0.000	0.000	0.000	0.000	
ES UP DEC	3.769	0.000	0.000	0.000	0.000	
ES MED VAL	3.267	0.000	0.000	0.000	0.000	
ES LOW DEC	2.661	0.000	0.000	0.000	0.000	
EX SYS STS	9.019	7.579	4.135	3.023	2.023	1.023
AND STATIS	-174.636	8.052	6.531	3.448	2.264	5.591

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	0.000	0.000	37.181	64.077	74.476	0.000	0.000	0.000
VIRTUAL HT	0.000	0.000	252.879	341.414	400.636	0.000	0.000	0.000
TM DLY MS.	0.000	0.000	2.736	5.054	8.329	0.000	0.000	0.000
SKY WV LOS	1000.000	1000.000	111.556	116.888	121.226	1000.000	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	3.242	4.455	6.252	1000.000	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	2.538	9.753	1000.000	1000.000	1000.000
TRNSMSN LS	1000.000	1000.000	123.816	132.899	146.250	1000.000	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	27.222	18.139	4.788	-1000.000	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-100.806	-109.888	-123.240	-1000.000	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	62.457	53.375	40.023	-1000.000	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.951	.504	.498	0.000	0.000	0.000
FRACT S/N	0.000	0.000	.780	.427	.019	0.000	0.000	0.000
RELIABILITY	0.000	0.000	.742	.215	.009	0.000	0.000	0.000
SERV. PROB	0.000	0.000	.146	.001	0.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=114.1 UD=110.1 LD=118.1 TIM DLY MS= 2.736  
 ANGLE OF ARRIVAL SKYWAVE= 37.2 NOISE LEVEL= -153.3 CIRCUIT RELIABILITY= .78  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 266.8

Figure 20. Output of air/ground model for circuit (17) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 88.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTER	45.0	10.0	1.0	86.5	785.8
RECEIVER	45.0	20.0	1.0	273.5	785.8

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPDW	MP-TMDLY
11.0	.200	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	392.896	196.448	589.344	392.896	392.896	
LATITUDE	45.109	45.082	45.082	45.109	45.109	
LONGITUDE	-15.000	-12.498	-17.502	-15.000	-15.000	
GEOM. LAT.	45.149	45.620	44.627	45.149	45.149	
TIME HOURS	12.000	0.000	0.000	0.000	0.000	
ABSORP FAC	.807	0.000	0.000	0.000	0.000	
E LAYER CR	2.997	0.000	0.000	0.000	0.000	
F LAYER RT	222.036	0.000	0.000	0.000	0.000	
HT OF FMAX	278.762	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.298	0.000	0.000	0.000	0.000	
F LAYER CT	10.236	0.000	0.000	0.000	0.000	
ES UP DEC	3.771	0.000	0.000	0.000	0.000	
ES MED VAL	3.271	0.000	0.000	0.000	0.000	
ES LOW DEC	2.661	0.000	0.000	0.000	0.000	
EX SYS STS	9.022	7.823	4.134	3.022	2.022	1.022
AND STATIS	-174.583	8.056	6.534	3.462	2.254	5.598

	E MODES			F MODES			EF MODES	
NO OF HOPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	0.000	0.000	29.956	54.882	69.788	0.000	0.000	0.000
VIRTUAL HT	0.000	0.000	242.938	293.733	376.903	0.000	0.000	0.000
TM DLY MS.	0.000	0.000	3.139	4.766	8.035	0.000	0.000	0.000
SKY WV LOS	1000.000	1000.000	112.749	116.377	120.914	1000.000	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	3.853	4.880	6.415	1000.000	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	8.670	10.394	1000.000	1000.000	1000.000
TPNSMSN LS	1000.000	1000.000	125.624	138.949	146.745	1000.000	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	25.414	12.090	4.293	-1000.000	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-102.614	-115.938	-123.735	-1000.000	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	60.645	47.321	39.524	-1000.000	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.994	.599	.499	0.000	0.000	0.000
FRACT S/N	0.000	0.000	.722	.173	.014	0.000	0.000	0.000
RELIABILITY	0.000	0.000	.717	.104	.007	0.000	0.000	0.000
SERV. PROB	0.000	0.000	.076	.000	0.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=115.6 UD=111.6 LD=119.6 TIM DLY MS= 3.139  
 ANGLE OF ARRIVAL SKYWAVE= 30.0 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .72  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 298.3

Figure 21. Output of air/ground model for circuit (18) in Table 3, 11 MHz.

TIME= 11.00UT DATE=12/15/82 SSN= 98.

	LAT.	LONG. DEG. E	HEIGHT	AZMOUTH	DIST. KM
TRANSMITTR	45.0	10.0	1.0	85.7	942.7
RECEIVER	45.0	22.0	1.0	274.3	942.7

FREQ-MHZ	PWR-KW	REQ S/N-DB	MM-NOISE	REQ-REL	MP-SIGPOW	MP-TMDLY
11.0	.200	55	SUBURBAN	90	4.0	2.000

	1	2	3	4	5	
DIST FM TX	471.343	235.671	707.014	471.343	471.343	
LATITUDE	45.157	45.118	45.118	45.157	45.157	
LONGITUDE	-16.000	-12.996	-19.004	-16.000	-16.000	
GEOM. LAT.	44.997	45.555	44.366	44.997	44.997	
TIME HOURS	12.067	0.000	0.000	0.000	0.000	
ABSORP FAC	.806	0.000	0.000	0.000	0.000	
E LAYER CR	2.992	0.000	0.000	0.000	0.000	
F LAYER BT	222.126	0.000	0.000	0.000	0.000	
HT OF FMAX	279.352	0.000	0.000	0.000	0.000	
GYRO FREQ.	1.301	0.000	0.000	0.000	0.000	
F LAYER CT	10.247	0.000	0.000	0.000	0.000	
ES UP DEC	3.769	0.000	0.000	0.000	0.000	
ES MED VAL	3.270	0.000	0.000	0.000	0.000	
ES LOW DEC	2.658	0.000	0.000	0.000	0.000	
EX SYS STS	9.021	7.811	4.126	3.021	2.021	1.021
AND STATIS	-174.530	8.061	6.537	3.476	2.245	5.605

	E MODES			F MODES			EF MODES	
NO OF HDPS	1.000	2.000	1.000	2.000	3.000	0.000	0.000	0.000
TK OFF ANG	0.000	0.000	24.830	47.899	64.091	0.000	0.000	0.000
VIRTUAL HT	0.000	0.000	237.394	274.595	341.457	0.000	0.000	0.000
TM DLY MS.	0.000	0.000	3.591	4.891	7.581	0.000	0.000	0.000
SKY WV LOS	1000.000	1000.000	113.918	116.603	120.409	1000.000	1000.000	1000.000
ABSRP LOSS	1000.000	1000.000	4.471	5.345	6.671	1000.000	1000.000	1000.000
GND REF LS	1000.000	1000.000	0.000	8.520	17.516	1000.000	1000.000	1000.000
TRNSMSN LS	1000.000	1000.000	127.410	139.488	153.618	1000.000	1000.000	1000.000
FIELD STRN	-1000.000	-1000.000	23.629	11.550	-2.580	-1000.000	-1000.000	-1000.000
SIG POWER	-1000.000	-1000.000	-104.399	-116.478	-130.607	-1000.000	-1000.000	-1000.000
S/N IN DB.	-1000.000	-1000.000	58.856	46.777	32.648	-1000.000	-1000.000	-1000.000
FRACT DAYS	0.000	0.000	.994	.714	.507	0.000	0.000	0.000
FRACT S/N	0.000	0.000	.659	.154	.000	0.000	0.000	0.000
RELIABILITY	0.000	0.000	.655	.110	.000	0.000	0.000	0.000
SERV. PROB	0.000	0.000	.036	0.000	0.000	0.000	0.000	0.000

MODE= 1 F MULTI PTH PROB= .01 PATH LOSS=117.4 UD=113.4 LD=121.4 TIM DLY MS= 3.591  
 ANGLE OF ARRIVAL SKYWAVE= 24.9 NOISE LEVEL= -163.3 CIRCUIT RELIABILITY= .66  
 ANGLE OF ARRIVAL DIRECT= -.0 GROUNDWAVE LOSS= 329.4

Figure 22. Output of air/ground model for circuit (19) in Table 3, 11 MHz.

ground program take about 1 ms for each frequency and path. This is about one hundred times faster than the calculations given by GWSNR in OT Technical Memorandum 78-247.

It is reasonable to expect that the computer time required to undertake specific calculations will vary with different main-frame machines. Thus the results quoted above should be treated as illustrative rather than absolute.

The accuracy of the HF air-to-ground calculations are as important as the speed. To determine this accuracy, the calculated results of the air-to-ground program were compared with the HFUFES and GRWSN results for a large number of cases.

The most meaningful comparisons between results of the air-to-ground program and the more general skywave and groundwave programs are the various loss parameters. Differences in the values of the loss parameters are caused principally by the grid system invoked in the air-to-ground program. An example of the relative accuracy of the air-to-ground program is given in Table 6, which shows the root-mean-square errors in decibels for the 17 circuits listed in Table 3 with path lengths less than 2000 km. In all cases the errors in skywave losses and absorption losses were less than 0.5 dB for each circuit. The errors in ground reflection losses for skywave circuits are generally less than one-half of 1 dB, except when the reflection area crosses a boundary between land or sea or good earth to poor earth. The interpolation listed in subroutine HFSKGD makes the transition across one grid interval, whereas in the HFUFES program the transition is made in a very short interval. If the grid interval was decreased, this error could be decreased. In general, the skywave portion of HFSKGD is quite accurate, and if more accuracy is needed, a more dense grid can be implemented.

The groundwave errors are displayed at the bottom of Table 6. They are the errors over the 17 paths and vary from 1 to 8 dB. For low antennas and distances less than 1000 km, the errors for frequencies above 4 MHz were less than 2 dB. At distances greater than 1000 km and antennas above 5 km, the errors increase considerably. To improve the accuracy of the predictions in these cases requires more effort to further expand and develop the model. It should be borne in mind that one of the objectives of this program was to develop a fast method to compute HF circuit performance. When trade-offs between speed and accuracy had to be made, the decision always favored speed.

## 5. CONCLUSIONS AND RECOMMENDATIONS

An HF propagation prediction program for rapid calculations of air-to-ground HF circuit parameters has been described. The program is optimized to enable the

Table 6. RMS Errors in Decibels for Air-to-Ground Loss Parameters for 17 HF Circuits, 4 Seasons, 2 Hours, and 1 Solar Activity

Ionospheric Wave Error

- Skywave loss,  $L_{bf}$  : Less than 0.5 dB for each circuit.  
 Absorption loss,  $L_i$  : Less than 0.05 dB for each circuit.  
 Ground reflection loss,  $L_g$  : Less than 0.5 dB when not in a transition area.  
 Less than 7.0 dB in transition area.

Ground Wave

Frequency MHz	3	5	8	11	15	18	21	26
All circuits	6.3	4.4	4.3	5.8	4.5	4.6	4.7	4.7
Low antenna less than 1200 km distance	4.9	1.9	1.0	1.8	1.6	1.8	1.8	1.8
20 km antenna less than 1000 km distance	2.7	5.3	6.7	6.8	7.8	7.9	8.0	8.0

rapid calculation of a large number of circuits of various frequencies and lengths at the same universal time. The air-to-ground HF propagation program is derived from two propagation programs developed at the Institute for Telecommunication Sciences. The skywave portion of the air-to-ground HF propagation program follows from the HF MUFES program described by Barghausen et al. (1969). The groundwave portion of the air-to-ground propagation program is based upon the work of Berry (OT Technical Memorandum 78-247, January 1978). The air-to-ground model described herein is an order of magnitude faster than the antecedent programs.

Despite attempts to optimize the speed and accuracy of the calculations involved in the air-to-ground program, limitations to the program exist. As in the HF MUFES program, the ionization in the F1 layer is ignored. This could prove to be a significant limitation for circuits that are simulated for local summer conditions when the ionization in the F1 layer is a substantial fraction of that in the F2

region during the daytime. The F-layer ionization can effectively block radio waves from reaching the F2 region, thereby reducing the length of the propagation path for the frequencies reflected from the F1 layer.

The noise generated by aircraft operations is not included in the signal-to-noise ratio. Also, there is no height variation of the atmospheric noise and man-made noise in the program. These could prove to be substantial limitations to the accuracy of the simulated results for those cases involving platforms that are elevated above 5-10 km.

The accuracy of the predictions of the groundwave loss for distances greater than 1000 km and antenna heights above 5 km needs to be improved. This improvement may require using the exact equations. If this approach were adopted, it would come at considerable expense of the overall speed of the current air-to-ground program.

The limitations mentioned above should be removed by future work that is directed toward improving the HF air-to-ground propagation model.

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